		Final Voar (Government Colle Semester – VII) B. To	0 0	0,		ation	
		Fillar Fear ($\frac{\text{Semester} - \mathbf{VH}}{\text{EX2701: Data a}}$			ecommunica		
Te	aching Sche	me				Examinatio	on Scheme	
	tures	03 Hrs/week				CT - 1	15	
	orials	00 Hrs/week				CT - 2	15	
	al Credits	03				TA TA	10	
100		00				ESE	60	
						Duration of		30 Min
Co	urse Outcor	nes (CO)				•		
Stu	dent will be	able to						
1.	Relate Math	ematical concept	pts behind the cryptogra	phic algorithm				L2
			n using various Security					L3
3.	Develop tes	t beds in order to	o design network and see	curity experiment	nts/simulation	ons.		L3
			at comply with cyber see					L3
			y mechanisms like passv	vords, access co	ontrol mecha	nisms, firewa	lls etc.	L3
6.	Interpret sta	andard approach	es in cyber security					L4
				rse Contents				Hours
Un			cryptography techniqu		· – –		a (1	10
			Security Approaches, Fentiality, Integrability,					
		AAA (Collinut	acy Plain Text and C	inher Text Si	bstitution '	Techniques '	Transposition	
			c and Asymmetric key cr					
		tion Standards.		jptographij, to	I Dulu Liici	Sprion Stande	alas, i la tanée	
Un		et Security Pro	otocols:					08
			ocols and User Authentic				t Layer, TLS,	
			L Verses SET, 3-D Secu	re Protocol, Ele	ectronic Mon	ney		
Un		of Security:						08
			alls, IP Security, VPN, P					
			e Pitfalls. Operating Sys		Knowledge	of windows a	and Linux OS	
T Im		ity threats:	rdening (CIS bench mar	KS)				08
UI		v	and impacts, Detection	methods (Hone	whate Short) Defence ter	hniques	Võ
	~ 1		erability assessment and	•	V I	· · · · · · · · · · · · · · · · · · ·		
		s (APT)	erability assessment and	Tenetration Te		1 <i>cst)</i> , <i>1 covance</i>	e i ensistence	
Un		and Big Data	networks [.]					08
U		0	oud Security – AWS/Azu	re/Google, Mol	bile applicat	ion Security N	IIST	00
	standa	•	, a.a. 2000110j 11((2),1120		one appnead	1011 20001109 1		
Te	kt Books							
1.	Behrouz A.	Forouzan, Dede	ep Mukhopadhyay "Cry	ptography & No	etwork Secu	rity", Fourth	Edition, Tata N	/IcGraw
	Hill, New D							
2.	Douglas R.	Stinson, "Crypto	ography: Theory and Pra	ctice", Third Ed	dition, CRC	Press.		
			raphy and Network Secu				Education, Fou	ırth
	Edition,		,			, , , , , , , , , , , , , , , , , , , ,	2000000,100	
4.		"Cryntography	and Network Security"	2nd Edition T	ata McGraw	v Hill		
	ference Boo			, 211a Dattion, 1				
1.	-		, Springer. J. Daemen, V	Riimen				
<u>1.</u> 2.			matical Cryptography",		tein Pinher	Silvermman		
				~	, i ipiioi,	, on , en innull.		
<u>3.</u>	v	nic Cryptanalysi	is", CRC Press. A. Joux			1		1
	eful Links	, <u>1 - 1</u>	1	• /				
1.			http://cse29-iiith.vlabs.a					
2.	2014/index.	htm "Computer	electri cal-engineering-a Systems Security by Nic	ckolai Zeldovicl	h & James N	lickens, MIT'	,	
		.ac.in/cours es/1	06105031/ "Cryptograp					Т
3.		-Videos and PD	F					
	Kharagpur"		F	McfIV7UiHNu	Qg/v "Introc	luction to Crv	ptography by C	Christof

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	-	1	-	-	-	-	-	-	-	-	2	-	-
CO2	-	1	-	1	-	-	-	-	-	-	-	-	-	1	-
CO 3	-	-	1	-	-	-	-	-	-	-	-	-	-	1	-
CO 4	-	1	2	1	3	-	-	-	-	-	-	-	-	-	-
CO 5	-	-	-	2	-	-	-	-	-	-	-	-	-	-	-
CO 6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Total	3	4	3	5	3	-	-	-	-	-	-	-	2	2	-
Avg	3	1.33	1.5	1.25	3	-	-	-	-	-	-	-	2	1	-
%	99.99	44.32	49.99	41.66	99.99	-	-	-	-	-	-	-	66.66	33.33	-

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	5		2	10
Understand	5	5	3	10
Apply	5	5	3	15
Analyze	-	5	2	25
Evaluate	-	-	-	-
Create	_	-	_	-
TOTAL	15	15	10	60

			lege of Engineerin			
	Final Year (Tech. Electronics a e and Video Proces	and Telecommunicat	tion	
Teachi	ng Scheme	EA2702.IIIag		Examination	Scheme	
Lecture				CT – 1	15	
Tutoria				CT – 2	15	
Total C	bredits 03			ТА	10	
				ESE	60	
				Duration of E	ESE 02 Hr	s 30 Min
	Outcomes (CO)					
	t will be able to		· · · ·			
1. Sun 2. An	mmarize fundamental co alyze images in "Spatia	ncepts of a digital ima	ge processing system	l.		L2 L4
	aluate the techniques for					L4 L5
	tegorize various compre					L3 L4
	strate the various techn					L4
6. Cre	eate report and presentat	on on recent trends in	Image and video pro	cessing		L6
		С	ourse Contents			Hours
Unit 1				a		06
				, Components, Elements and Quantization, Rel		
				Color models, Pseudo co		
	Processing.					
Unit 2						06
	1-D DFT, 2-D Discret	te Fourier Transform a	Ind Its Inverse, Some	Properties of 2D DFT, Orthogonal, Euclidean,	Affina	
TT 4 3			orm. Transformation:	Orthogonal, Euclidean,	Anne.	00
Unit 3			aw transform Histor	gram equalization and	Histogram	08
	Specification.	Transform, Tower E	aw transform, mstog	grann equalization and	mstogram	
	Spatial Domain: Bas			patial Filtering, Generat	ing Spatial	
		ing and Sharpening Sp				
				omain, Smoothing and S , Laplacian, Unsharp M		
	Homomorphic filters	ers – Idear, Dutterwort	i and Gaussian inters	, Laplaciali, Ulisharp M	asking and	
Unit 4	Image Restoration a	nd Image compression	on:			06
			Order Statistics– Adap	ptive filters – Band reje	ct Filters –	
	Band pass Filters – N				c	
	-	• •		cy-Measuring image in		
		compression, JPEG-20	6	coding, LZW coding, R	un-Length	
Unit 5		al Video and Video H	<u> </u>			06
011100	0		e	or, dynamic Range, bit-o	lepth.	
	Video Processing- Vi	deo sampling, flicker,	spatial frequency resp	ponse, Motion modeling	g and	
			ng, Parametric motior	n estimation, Video filte	ring,	
	Deinterlacing, And D					
Unit 6	-				1 4	08
				pression, H.263/MPEC deo compression, Scala		
	· · ·	esilient compression,		aco compression, scala		
Fext Bo						_1
	nzalez and Woods, "Dig	ital Image Processing	', Pearson Education,	India, Third Edition.		
2. An	il K. Jain, "Fundamenta	s of Image Processing	", Prentice Hall of In	dia, First Edition. 1989		
	M. Tekalp, "Digital Vic					
Referen	ce Books					
	R. Castleman, "Digital i					
2. W	Pratt, "Digital Image	Processing, Wiley P	ublication, 3 rd Edit	ion, 2002		
3. Y.	Wang, J. Ostermann,	and YO. Zhang "V	deo Processing and	Communications" P	rentice Hall	. 2002.
	3N 0-13-017547-1		and a rocessing and	. communications , I	- milee mult	., 2002.
Useful L						
	'Kharagpur: https://npte	.ac.in/courses/117/10	5/117105079/			
	Kharagpur: https://npte				-	
	• •					

- **3.** IIT Kanpur: https://nptel.ac.in/courses/117/104/117104020/
- 4. https://web.stanford.edu/class/ee392j/
- 5. https://www.coursera.org/learn/digital

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	1	1	1	-	-	-	-	-	-	-	2	1	-
CO 2	3	2	1	2	2	-	-	-	-	-	-	-	2	-	1
CO 3	2	2	2	2	2	-	-	-	-	-	-	-	2	1	2
CO 4	2	2	2	2	2	-	-	-	-	-	-	-	2	1	2
CO 5	3	2	2	2	2	-	-	-	-	-	-	-	2	1	2
CO 6	2	2	2	2	2	-	-	-	2	2	-	1	2	-	2
	15	12	10	11	11	-	-	-	2	2	-	1	12	4	9
	2.5	2	1.6	1.83	1.83	-	-	-	2	2	-	1	2	1	1.8
%	83.3	66.6	53.3	61	61	-	-	-	66.6	66.6	-	33.3	66.6	33.3	60
1 – Low	2 - M	edium3	– Hig	h											

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	05	-	-	05
Understand	05	-	-	10
Apply	05	-	-	10
Analyze	-	05	05	15
Evaluate	-	05	05	15
Create	-	05	-	05
TOTAL	15	15	10	60

		Government College of En				
		(Semester – VII) B. Tech. Elec		ecommunication		
		703:Fiber Optics & Optical N	etwork			
	g Scheme			Examination Sch		
Lectures	02 Hrs/week			CT – 1	15	
Tutorials				CT – 2	15	
Total Cre	edits 02			TA	10	
				ESE	60	20.14
0				Duration of ESE	02 Hrs	30 Min
	Outcomes (CO) will be able to					
		an antia avatam				T 1
	narize the basic of fib	naracteristics of optical system				L1 L2
	· ·	ters of optical networks and measure	romont toohniquo	0		L2 L3
	ate analog and digita		irement technique	5.		L5
	yze the fiber optics ne	1 5				L3 L4
		concept to various optical applicat	iona			L4 L3
0. Appr	y the advance optical	Concept to various optical applicat				Hours
Unit 1	Introduction to Fibe		ents			06
		t, Optics, Optical Fibers: Manufactu	ring Types & Tr	ansmission Characte	ristics	00
1	Optical Fiber waveg	uide: Ray theory transmission,	Electromagnetic	mode theory for	optical	
		ources: Light-Emitting Diodes and				
	emitting LEDs, super	luminescent diode, Photo detector				
	of photo detectors					
	Optical Systems & P					05
		gnal degradation in optical fibers, p				
		ical link, analog optical link, optical link		ptical SNR, Optical	Time	
	Optical Fiber Measu	r (OTDR), non linear effects in fib	eroptics			07
		easurement, Fiber Dispersion me	easurement Fiber	· refractive index	nrofile	07
1	measurement. Fiber c	utoff wavelength measurement, F	iber numerical ap	erture measurement	. Fiber	
		t, Field measurement, Performance				
	budget, Rise time bud				1	
Unit 4	Fiber Optic Networl	KS:				06
		cepts, Optical network transmiss				
	-	NET/SDH, Optical switching netw	-	work deployment, (Optical	
	·	tection, restoration and survivabili	ty			
	Advanced Optical Sy					04
		n formats, Demodulation scheme				
		annel capacity, Wavelength conv	erters, Ultrafast o	optical switching, O	ptical	
		otics Security concerns				
Text Boo		·	·· ·· ·· ·· ··	11		<u> </u>
-	· •	ommunications. Principle and Prac	<i>i</i>			
	e ,	pptic Communication Systems,' 4th	, ,			
	· · ·	communications", Tata McGraw-H	ill Education, 4th	Ed., 2008.		
D . C		"(Later lestion to Eiler Oution")	<u></u>			
Reference		n, "Introduction to Fiber Optics", (
1. A.Gh		$(\cdot D1 \cdot 1T 1 1) O$. 2016		
1. A.Gh 2. Fedor	r Mitschke, "Fiber Op	tics: Physics and Technology", Spi		,		
 A.Gh Fedor Jeff H 	r Mitschke, "Fiber Op Iecht, "Understanding	tics: Physics and Technology", Spi Fiber Optics", Laser Light Press,				1
 A.Gh Fedor Jeff H Useful L 	r Mitschke, "Fiber Op Iecht, "Understanding <mark>inks</mark>	Fiber Optics", Laser Light Press,	5th Edition, 2015			
1. A.Gh 2. Fedor 3. Jeff H Useful L I.	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117	5th Edition, 2015 101054/			
 A.Gh Fedor Jeff F Useful L From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https://	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810	5th Edition, 2015 101054/ 6167/			
 A.Gh Fedor Jeff H Useful L From From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks ITT Bombay:- https ITT, Madras:- https:// ITT Roorkee:- https://	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810 /nptel.ac.in/courses/115/107/11510	5th Edition, 2015 101054/ 6167/ 17095/			
 A.Gh Fedor Jeff H Useful L From From From From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https IIT, Madras:- https:// IIT Roorkee:- https:// IIT Bombay:-https://	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810 /nptel.ac.in/courses/115/107/11510 nptel.ac.in/courses/117/101/11710	5th Edition, 2015 101054/ 6167/ 17095/ 1002/			
 A.Gh Fedor Jeff H Useful L From From From From From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https:// IIT, Madras:- https:// IIT Roorkee:- https:// IIT Bombay:-https:// IIT Kanpur:-https://n	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810 /nptel.ac.in/courses/115/107/11510 nptel.ac.in/courses/117/101/11710 ptel.ac.in/courses/117/104/117104	5th Edition, 2015 101054/ 6167/ 7095/ 1002/ 127/			
 A.Gh Fedor Jeff H Useful L From From From From From From From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https:// IIT, Madras:- https:// IIT Roorkee:- https:// IIT Bombay:-https://n IIT Kanpur:-https://n IIT Kanpur:- https://r	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810 /nptel.ac.in/courses/115/107/11510 nptel.ac.in/courses/117/101/11710	5th Edition, 2015 101054/ 6167/ 7095/ 1002/ 127/			
 A.Gh Fedor Jeff H Useful L From From From From From From From From 	r Mitschke, "Fiber Op Hecht, "Understanding inks IIT Bombay:- https:// IIT, Madras:- https:// IIT Roorkee:- https:// IIT Bombay:-https:// IIT Kanpur:-https://n	Fiber Optics", Laser Light Press, ://nptel.ac.in/courses/117/101/117 nptel.ac.in/courses/108/106/10810 /nptel.ac.in/courses/115/107/11510 nptel.ac.in/courses/117/101/11710 ptel.ac.in/courses/117/104/117104	5th Edition, 2015 101054/ 6167/ 7095/ 1002/ 127/			

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓									9						
CO 1	3	1	1	-	-	-	-	-	1	-	-	-	-	2	-
CO 2	3	2	2	1	1	-	1	-	-	-	-	-	-	2	-
CO 3	2	2	-	2	3	-	1	-	-	-	-	-	-	2	1
CO 4	2	2	2	1	2	-	-	-	1	-	-	-	-	2	-
CO 5	2	2	1	2	-	-	-	-	-	-	-	-	-	2	1
CO 6	3	2	1	-	1	-	-	-	1	-	-	-	-	2	1
	15	11	7	6	6	0	2	0	3	0	0	0	0	12	3
	2.5	1.83	1.4	1.5	1.5	0	1	0	1	0	0	0	0	2	1
%	83.33	61.11	46.66	50	50	0	33.33	0	33.33	0	0	0	0	66.66	33.33
1 – Low	2 - M	edium3	– Hig	h											

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	05	-	-	05
Understand	05	-	-	10
Apply	05	-	-	10
Analyze	-	05	05	15
Evaluate	-	05	05	15
Create	-	05	-	05
TOTAL	15	15	10	60

Tee		Final Year (Government College Semester – VII) B. Tech				
Tee		X	2704: Artificial Intellige				
	ching Sche				Examination Sch	eme	
	tures	03 Hrs/week			CT – 1	15	
	orials	00 Hrs/week			CT = 1 CT = 2	15	
	al Credits	03			TA	10	
100					ESE	60	
					Duration of ESE	00 Hrs 3	0 Mir
Cor	urse Outcon	nes (CO)			D unution of LDL	02 1110 0	0 10111
	dent will be						
1.			atistics techniques				L3
2.			non-linear regression techni	iques to formulate foreca	sting models		L4
3.			g methods for classification	1	6		L4
4.			for classification of given da	ata			L4
5.			ecurrent neural networks to		18		L5
6.	Justify deep	o learning algori	thms to perform regularizati	lon			L5
		6.6	, <u>,</u>	Contents			Hour
Un	it 1 Review	v of Sampling.	Estimation and Inferential		on to Machine Lea	arning:	
Un	and f to reducti						5
	Covar multip nets, n	iance and corre le regression me onlinear regressi	lation, hypothesis testing o thods, polynomial regression, classification, forecasting	on, regularization metho			6
Un	Naïve estima Suppor feature	tes, Feature select rt Vector Machine space, SVM for	r – Model assumptions, Pr ction: Mutual information nes - Linear learning machin classification and regression	es and Kernel space, Ma	king Kernels and w	orking in	7
UI	Distan Iterativ Constr quality Triang Neight	ve distance-base ucting a hierarce of clustering. I ulations, K-Nea	fferent clustering methods (ed clustering, Dealing w hical cluster, K-Medoids, 1 K-Nearest Neighbors - Com rest Neighbor algorithm, ction/dimensionality reduction	ith continuous, catego k-Mode and density-bas nputational geometry; V Aspects to consider v	rical values in K sed clustering, Mea oronoi Diagrams, I while designing K	K-Means, asures of Delaunay K-Nearest	10
Un	it 5 Artific What i Branch Neural Convo	Fial Intelligence s AI ? History of a and Bound, Gra	and applications using Ne Artificial Intelligence, Apprendient Descent		Divide and Conquer		
		eter tuning, Eme ent Neural Netw	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu	I, Backpropagation n, Text classification, Im	age classification ar	nd hyper-	9
	Recurr Foreca it 6 Deep I Auto-e	eter tuning, Eme ent Neural Netw sting Learning : ncoders and u	- Perceptron and MLP, FFN tworks - Image classification rging architectures	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and	age classification ar -Term Memory, Tir	nd hyper- ne Series	9 5
Гех	Recurr Foreca it 6 Deep I Auto-e Regula tt Books	eter tuning, Eme ent Neural Netw sting Learning : ncoders and u urization - Dropo	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization.	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and	age classification ar -Term Memory, Tir semi-supervised	nd hyper- ne Series learning,	
<mark>Гех</mark> 1.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS,	eter tuning, Eme ent Neural Netw sting Learning : mcoders and u rization - Dropo "Advance Engi	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization.	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer	age classification ar -Term Memory, Tir semi-supervised	nd hyper- ne Series learning, 2006	
Tex 1. 2. 3.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics",	eter tuning, Eme ent Neural Netw sting Learning : mcoders and u rization - Dropo "Advance Engi and Kjell Johnso Lelleher, Brian 2015, The MIT I	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Macl	age classification ar -Term Memory, Tir semi-supervised hth revised edition,2 inting 2018 edition hine Learning for	nd hyper- ne Series learning, 2006 Predictiv	5 ze Da
Tex 1. 2. 3. 4.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel	eter tuning, Eme ent Neural Netw sting Learning : mcoders and un rization - Dropo "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT H low, Yoshua Be	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, "	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Macl	age classification ar -Term Memory, Tir semi-supervised hth revised edition,2 inting 2018 edition hine Learning for	nd hyper- ne Series learning, 2006 Predictiv	5 ze Da
Tex 1. 2. 3. 4. Ref	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel cerence Boo	eter tuning, Eme ent Neural Netw sting Learning : mcoders and us urization - Dropo "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT H low, Yoshua Be ks	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press ngio and Aaron Courville, "	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Mack	age classification ar -Term Memory, Tir semi-supervised <u>hth revised edition,2</u> <u>inting 2018 edition</u> hine Learning for <u>IT Press; Illustrated</u>	nd hyper- me Series learning, 2006 Predictiv edition, 2	5 7e Da
Tex 1. 2. 3. 4. Ref 1.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel cerence Boo Trevor Hast	eter tuning, Eme ent Neural Netw sting Learning : .ncoders and u urization - Dropo "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT H low, Yoshua Be ks ie, Robert Tibsh	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press ngio and Aaron Courville, " irani, and Jerome Friedman	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Mack Deep Learning", The M	age classification ar -Term Memory, Tir semi-supervised <u>hth revised edition,2</u> <u>inting 2018 edition</u> hine Learning for <u>IT Press; Illustrated</u>	nd hyper- me Series learning, 2006 Predictiv edition, 2	5 7e Da
Tex 1. 2. 3. 4. Ref 1.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel terence Boo Trevor Hast Inference, a	eter tuning, Eme ent Neural Netw sting Learning : mcoders and un rization - Dropo "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT H low, Yoshua Be ks ie, Robert Tibsh nd Prediction",	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press ngio and Aaron Courville, " irani, and Jerome Friedman Springer; 2nd edition, 2016	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Macl Deep Learning", The M	age classification ar -Term Memory, Tir semi-supervised hth revised edition,2 inting 2018 edition hine Learning for IT Press; Illustrated stical Learning: Data	nd hyper- me Series learning, 2006 Predictiv edition, 2 a Mining,	5 7e Da
Tex 1. 2. 3. 4. Ref 1. 2.	Recurr Foreca it 6 Deep I Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel Cerence Boo Trevor Hast Inference, a Stuart Russ	eter tuning, Eme ent Neural Netw sting Learning : mcoders and un rization - Dropo "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT I low, Yoshua Be ks ie, Robert Tibsh nd Prediction", ell and Peter Nor	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu- nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press ngio and Aaron Courville, " irani, and Jerome Friedman. Springer; 2nd edition, 2016 vig, "Artificial Intelligence	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and hand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Macl Deep Learning", The M	age classification ar -Term Memory, Tir semi-supervised hth revised edition,2 inting 2018 edition hine Learning for IT Press; Illustrated stical Learning: Data Pearson, 3rd editio	nd hyper- me Series learning, 2006 Predictiv edition, 2 a Mining, n, 2010	5 7e Da 2016
Tex 1. 2. 3. 4. Ref 1. 2. 3.	Recurr Foreca it 6 Deep J Auto-e Regula t Books H.K.DASS, Max Kuhn a John D. K Analytics", Ian Goodfel Cerence Boo Trevor Hast Inference, a Stuart Russe Aurélien Gé	eter tuning, Eme ent Neural Netw sting Learning : mcoders and un urization - Dropo . "Advance Engi and Kjell Johnso Celleher, Brian 2015, The MIT H low, Yoshua Be ks ie, Robert Tibsh nd Prediction", ell and Peter Non Fron, "Hands-Om	- Perceptron and MLP, FFN tworks - Image classification rging architectures orks - Building recurrent neu nsupervised learning, Stac ut and Batch normalization. neering Mathematics", S.Ch n, "Applied Predictive Mod Namee, Aoife D'arcy, " Press ngio and Aaron Courville, " irani, and Jerome Friedman Springer; 2nd edition, 2016	I, Backpropagation n, Text classification, Im ural network, Long Short ked auto-encoders and nand publications, Fifteer leling", Springer; 2nd pr Fundamentals of Macl Deep Learning", The M , "The Elements of Statis : A Modern Approach", ikit-Learn and TensorFlo	age classification ar -Term Memory, Tir semi-supervised hth revised edition,2 inting 2018 edition hine Learning for IT Press; Illustrated stical Learning: Data Pearson, 3rd editio	nd hyper- me Series learning, 2006 Predictiv edition, 2 a Mining, n, 2010	5 7e Da 2016

- 1. https://medium.com/@luckecianomelo/mathematics-for-machine-learning-review-part-i-fef3ed813f21
- 2. http://www.amlbook.com/support.html#_echapters
- 3. https://www.khanacademy.org/math/calculus-home/multivariable-calculus
- 4. https://nptel.ac.in/courses/106/106/106106139/

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	2	1	1	-	-	-	-	-	-	-	2	-	-
CO2	3	2	2	2	2	-	-	-	-	-	-	-	2	-	-
CO 3	2	2	2	2	2	-	-	-	-	-	-	-	2	-	-
CO 4	2	3	2	2	2	-	-	-	-	-	-	2	2	-	-
CO 5	2	2	2	2	2	-	-	-	-	-	-	-	2	-	1
CO 6	2	3	2	2	2	-	-	-	-	-	-	2	2	-	1
	2.33	2.33	2	1.83	1.83	-	-	-	-	-	-	2	2	-	1
%	77.66	77.66	66.66	61	61	-	-	-	-	-	-	66.66	66.66	-	33.33
1 – Low	2 – Mee	dium3 –	High												

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				
Understand	5			10
Apply	5	5	4	10
Analyze	5	5	2	10
Evaluate		5	2	10
Create			2	10
TOTAL	15	15	10	60

			Government						
	F	× *					ecommunication		
			EX2715: Mult	irate Signal	Processi	ng and W			
	g Scheme						Examination Sch	-	
Lectures		2 Hrs/week					CT - 1	15	
Tutorials		1 Hrs/week					CT-2	15	
Total Cre	edits 03	3					TA ESE	10 60	
							Duration of ESE	00 Hrs 3	30 Min
Course O	utcomes ((CO)					Duration of LDL	02 1115 .	
Student wi									
1. Demo	onstrate M	Iultirate Signa	al Processing and	its applicatio	ons.				L2
			ver spectrum estir		al process	sing application	tions.		L3
			nd optimum linea						L5
			Fourier Transform	n and the signi	ificance of	f Wavelets.			L2
	yze Haar v					-			L4
6. Creat signa		nd presentation	on on application		-	ools to speed	ch, audio, image and	d video	L6
				Course Co	ontents				Hours
		Signal Proc			-1-4				5
			or, Multistage I				n, Sampling Rate C	onversion nposition,	
			ate Signal Process			manon , I	i orypnase Decol	nposition,	
		ectrum Estin							7
]	Non Parai	metric Metho	d of Power Spec				odified Periodogram		
	Method,	Welch's Met	thod, Blackman-	Tukey Appro	oach Pai	rametric M	lethods of Power	Spectrum	
							ule-Walker Equati tion, Autoregressiv		
			mation Eigen Ar					c wioving	
			l Optimum Line		~				7
							inear Prediction, S		
			R Lattice and AF	RMA Lattice	Ladder F	ilters, Wei	iner Filters for Filt	ering and	
	Prediction Wavelet:	l							6
		ion-limitation	of fourier transfo	orm. Origin o	f Wavelets	s .Haar Way	velet, Dyadic Wave	let.	U
			of Haar Wavelets				jua interest	2	
	Filter Bar								5
		on to Filter B	ank, Haar Analys	sis Filter Bank	c in Z-don	nain ,Haar S	Synthesis Filter Ban	k in Z-	
	domain. Tutorials y	will be based	on problem solvi	ng in multirat	te signal n	rocessing r	ower spectrum		
							video compression,		
			11	1		U .	rocessing tools to		
			nd video signals			0 1	U		
Text Boo	oks								
		and Aditya al	bhyankar Multire	solution and N	Multirate S	Signal Proce	essing McGraw Hil	ll Educatio	on; First
	on ,2017								
			of Signal Process	•			tion, 1999		
		than, "Multira	ate Systems and H	filter Banks,"	Prentice H	Hall, 1999			
Reference 1. M. V		Kovacevic ar	nd V. K. Goval"	The World of	Fourier a	nd Wavelet	s: Theory, Algorith	ms and	
Appli	ications"		•				• •		1
			he World accordi ess (Private) Indi			y of a Math	ematical Technique	e in the ma	akıng",
		Rao and Ajit tion Asia 200		-Wavelet Tran	nsforms , ·	—Introduct	ion to Theory and A	Application	ns∥,
4 Emm 2008		feachor, Barr	rie W. Jervis, —D	Digital Signal	Processing	g A Practica	ll Approach∥, Pearso	on Educat	ion
Useful L									
	<u> </u>		7/101/11710100						
			atch?v=_MdjuI4	7k8E&list=R	DCMUCY	alWtI-vb	bx-		
anHd	lmpNfA&	<u>start_radio=1</u>	<u>&t=13s</u>						

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	3	-	-	-	-	-	-	-	-	-	-	2	2	-
CO2	2	2	2	-	-	-	-	-	-	-	-	-		2	-
CO 3	2	1	3	2	-	-	-	-	-	-	-	-	-	1	1
CO 4	3	2	2	2	-	-	-	-	-	-	-	-	-	2	2
CO 5	2	2	2	-	-	-	-	-	-	-	-	-	-	-	2
CO 6	3	2	2	1	3	-	-	-	2	2	-	-	3	1	2
total	14	12	11	5	3	-	-	-	2	2	-	-	5	8	7
avg	2.33	2	2.22	1.6	1	-	-	-	1	1	-	-	2.5	1.6	1.75
%	77.6	66.66	74	53.3	33.3	-	-	-	33.3	33.3	-	-	83.3	53.33	58.3

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	-	-	-	10
Understand		05	05	10
Apply	05	05	05	10
Analyze	05	05	-	10
Evaluate	05		-	10
Create	-	-	-	10
TOTAL	15	15	10	60

		Government College of Engine	ering, Kara	nd		
	Final Year (S	Semester – VII) B. Tech. Electron		ecommunication		
		EX2725: Soft Computing	g.			
	g Scheme			Examination Sch	r	
Lectures				CT – 1	15	
Tutorials				CT – 2	15	
Total Cr	edits 03			ТА	10	
				ESE	60	
Course	Outcomes (CO)			Duration of ESE	02 Hrs	30 Min
	will be able to					
	ify soft computing tech	niques				L3
		uncertainty in engineering				L3
		ble for Fuzzy decision making.				L3 L4
<u> </u>	y genetic algorithms to					L3
r r -		· ·				L3 L4
		ols to solve real life problems	- 4			L4 L6
6. Crea	te report and presentation	on on recent development in soft comp	uting.			
TT •4 4		Course Contents				Hours
Unit I	Introduction to Soft C		11 1		<i>.</i> .	4
		? Differences between soft computing		nputing, Soft Comp	uting	
Unit 2		n soft computing, Applications of Soft	Computing.			7
Unit 2	Fuzzy logic:	ogic. Fuzzy sets: union ,intersection co	mplement F	uzzy relations: Card	inality	/
		and Membership functions: Features, I				
	Defuzzification techniq		uzzincation	, v alue assignment	memous.	
	Mean membership, Cer					
Unit 3	Fuzzy Rules:					7
		positions. Reasoning: Categorical, Qu	alitative Svll	ogistic Dispositiona	1.	
		Takagi-Sugeno (TS)method. Fuzzy Dec				
		ttribute, Fuzzy Bayesian. Fuzzy logic			1 /	
Unit 4	Genetic Algorithms:					6
	Concept of "Genetics" a	and "Evolution" .GA Terminologies: In	dividuals ,G	enes, Fitness, Popu	lations.	
	GA operators: Encoding	g, Crossover, Selection, Mutation GA	algorithms: 1	messy, adaptive, Pai	allel,	
	real coded Genetic algo	rithim				
	Swarm Intelligence:					4
		intelligence. Co- relate the animal beha	avior in swar	m intelligence. parti	cle	
	swarm optimization, an	•				
Note	Tutorial will be based					
		ic and Genetic algorithm tool box in M			Fraffic	
		troller ,power system control, robotic				
		tworks, bidding strategies, immune sys				
T		. Collection of information about recen	it developme	nt in soft computing	5.	-
Text Bo		And the set of NL Oblight and the Deskiller of the				
		Author: S.N. Shivanandam Publication				
		h, Optimization And Machine Learnin	g, David E. (Goldberg, Pearson E	ducation	, 2002.
	ce Books					
	Computing, D. K. Pratil					
		Fuzzy sets & Fuzzy Logic, Theory	&			
	ications, PHI Publication	on, 1stEdition, 2009.		1		T
Useful I						
I. https	://nptel.ac.in/courses/10	06/105/10610517/3/				

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	2	2	-		-	-	-	2	-	2	2	2	-	
CO2	3	3	-	3		-	-	-	-	-	2	-	3		
CO 3	3	3	3	3		-	-	-	-	3	2	-	-		
CO 4	2	2	3	2			-	-	2	2	2	-	-		2
CO 5	-	3	3	-			-	-	3	-	2	-	-		
CO 6	2	2	2	2			-	-	-	-	2	2-	2		2
Total	12	15	13	10			-	-	7	-	12		7		4
Avg	2.4	2.5	2.6	2.5			-	-	2.33	2.5	2	2	2.33		2
%	80	83.33	86.66	83.33			-	-	77.77	83.33	66.66-	66.66	77.77		66.66

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	5			
Understand	5		2	10
Apply	5	5	2	10
Analyze		5	2	10
Evaluate		5	2	15
Create			2	15
TOTAL	15	15	10	60

					ngineering, Kara			
		Final Year			ctronics and Tele	ecommunication		
			EX2735	5: Mixed Signa	l IC Designing			
		g Scheme				Examination Sch		
	tures					CT – 1	15	
	orials					CT – 2	15	
Tot	al Cre	edits 03				TA	10	
						ESE Denotion of ESE	60	20 Min
Co	1100	Outcomes (CO)				Duration of ESE	02 Hrs	30 Min
		will be able to						
1.		erentiate between An	alog Digital and N	Mixed Signal CN	IOS Integrated Circ	nits		L4
2.		ly the MOS circuit fo	<u> </u>	v	tob integrated ene			L3
3.		lyze the parameters o						L4
4.		elop various data con	v	•				L3
5.		ain the integrated cir						L2
6.	Crea	te report and present	ation on recent adv	vances in mixed	signal design proces	sses		L6
				Course Con	tents			Hours
Un	it 1	Analog versus disci	rete time signals.			active resistances.	current	5
-	-	source and sinks, c						
		voltage reference, B	Beta-Multiple refer	enced self-biasin	g, Mixed signal lay	out issues.		
Un	it 2	Switched capacitor	s circuits, Switch	ed capacitors a	mplifiers, Switched	l capacitors filters	- Non	5
		idealities in switche	ed-capacitor filters	s; Switched cap	acitor filter archite	ctures; Switched-ca	apacitor	
		filter applications,	. 1 1			. 1 1.0	CMOG	0
Un	it 3	Trans-conductance operational amplifi						8
		oscillators, Voltage						
		PLLs, Delay Locke				- <u>-</u>		
Un	it 4	Basics of data conv	verters, Data conve					6
		Averaging, Success		ADCs, Dual slop	pe ADCs, Flash AD	Cs, Pipeline ADCs,	High-	
TT	•	resolution ADCs, D		F 1	<u> </u>			-
Un	it 5	The importance of differential signalin				signal integrity, cro	ss taik,	4
No	te	Tutorial will be ba	sed on implemen	tation of MOS	transistor, different	tial amplifier, com	parator,	
		switched capacitor,	PLL, ADC & D	AC etc. using M	MICROWIND / Ica	arus Verilog/ open	source	
		software Magic VL	SI (mentioned in u	seful links (3)) f	or physical design a	is per target specific	cation	
	Bool					U'11 0001		
		azavi, "Design of Ana	ě ě					
		W. Li and David E Books	boyce, CMOSC	ircuit Design, La	yout, Sumulation",	гпі Eaition, 2005		
1 .		Allen and D R Holb	erg "CMOS Anal	og Circuit Desig	" second edition (Oxford University I	Press 200)2
<u>1.</u> 2.		y, Meyer, Lewis and	-					
	Inte	rnational, 2002	-	-	0 0		•	
3.	CM 200	OS Circuit Design, L 9.	ayout and Simula	tion by R.Jacob l	Baker, Wiley India,	IEEE Press, Secon	d Edition	, reprint
4.		log VLSI Signal and	Information Proc	essing, Ismail an	d Faiz, Mc Graw-H	ill		
Usef	ul Li	ě ě						
		://nptel.ac.in/courses/	/117/101/1171011	05/				
2.	http:/	//www.ee.iitm.ac.in/~	nagendra/teaching	g.html				
	_	/opencircuitdesign.co						
4.	https:	://nptel.ac.in/courses/	/117/106/1171060	34/				
		-4						

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	2	1										3		
CO 2	3	2	1	1	2							1	3		2
CO 3	2	2	2	1	2							1	3		1
CO 4	2	2	2	1	2								2		1
CO 5	1	1			1								1		
CO 6	2	2	1		2				2	2		2			
avg	2	1.83	1.4	1	1.8				2	2		1.33	2.4		1.33
%	66.66	61.11	46.66	33.33	60				66.66	66.66		44.44	80		44.44
1-Low 2-	Medium	n 3-Hig	h												

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				
Understand	5			10
Apply	10	10		10
Analyze		5		20
Evaluate				20
Create			10	
TOTAL	15	15	10	60

				ege of Enginee	<u> </u>			
-		Final Year (Se	emester – VII) B. T			communication	1	
			EX2745:Au	tomotive Elect	ronics			
	hing Schem					Examination So		
Lectur Tutori		02Hrs/week 01Hrs/week				<u>CT - 1</u> CT - 2	15 15	
	Credits	03				$\frac{CI-2}{TA}$	10	
Total	Cleuits	03				ESE	60	
						Duration of ESE		s 30 Min
Cour	se Outcom					Duration of LoL	0211	5 50 Willi
	ent will be a							
1.			mponents and tools.					L3
2.		motive electron						L3
3.			ntrol, security and war	ning system.				L4
4.			lication, construction		n of different	sensors and actua	ators	L2
	usable in t	ypical automobi	le electronics.					
5.		ybrid and electi						L5
6.	Apply the	new trends in A	utomotive Electronic	vehicles				L3
			Cou	rse Contents				Hours
Unit 1								5
			ineering, vehicle spec					
		-	, transmission, steerin	g, suspension, br	akes, comfo	rt and convenienc	e	
Unit 2	systems.	sensors and act	motors					6
Unit 2			ectronics system requi	rements Batters	, starting an	l charging system	c	0
			ical transients, load-du					
			ostatic discharge and					
			tuators, smart sensors					
Unit 3		control system		.		2		7
	Chassis	control systems,	Digital engine contro	l systems, Introd	luction to aut	omotive controlle	ers,	
	(ABS) a	nti lock braking	system, (ESP) Electro	nic Stability Pro	gram , (TCS) Traction control		
			e cruise control, Active				X–by–	
			ve alarm systems, Vel					
			rking systems, Central				nts and	
			at belt lighteners and a	ur_hags Fault to				
	Vehicles		e	iii bugs, i duit te	olerant schen	nes, Autonomous		
	Basics o	•	C	in bugs, i uut te	olerant schen	nes, Autonomous		
I Init 4					blerant schen	nes, Autonomous		4
Unit 4		f EV and Hybr	id vehicles			·		4
Unit 4	Basic of	f EV and Hybr electrical and hy				·	rs,	4
	Basic of battery s	f EV and Hybr electrical and hy ystems.	id vehicles /brid vehicles, architec			·	rs,	4
Unit 4 Unit 5	Basic of battery s Trends	f EV and Hybr electrical and hy ystems. in Automotive	id vehicles /brid vehicles, architec Electronic vehicles	tures of EV/HEV	/, major type	s of traction motor		
	Basic of battery s Trends : Electron	f EV and Hybr electrical and hy ystems. in Automotive	id vehicles /brid vehicles, architec Electronic vehicles erence Suppression,	tures of EV/HEV	/, major type	s of traction motor	iic	
	Basic of battery s Trends Electron Dashboa	f EV and Hybr electrical and hy ystems. in Automotive nagnetic interf rd Instruments,	id vehicles brid vehicles, architec Electronic vehicles erence Suppression, Onboard Diagnostic S	Electromagnet	/, major type tic Compa , Warning S	s of traction motor ibility, Electron ystem, infotainme	nt	
	Basic of battery s Trends Electron Dashboa and Tele	f EV and Hybr electrical and hy ystems. in Automotive nagnetic interf rd Instruments, ematics, Vehicle	id vehicles /brid vehicles, architec Electronic vehicles erence Suppression, Onboard Diagnostic S e System of Systems	tures of EV/HEV Electromagnet System, Security in the Internet of	/, major type tic Compat , Warning S of Things, E	s of traction motor ibility, Electron ystem, infotainme nergy Manageme	ic nt nt	
	Basic of battery s Trends = Electron Dashboa and Tele Systems	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle , Advanced Driv	id vehicles brid vehicles, architec Electronic vehicles erence Suppression, Onboard Diagnostic S	Electromagnet System, Security in the Internet of (ADAS) and Aut	/, major type tic Compat , Warning S of Things, E	s of traction motor ibility, Electron ystem, infotainme nergy Manageme	ic nt nt	
	Basic of battery s Trends Electron Dashboa and Tele Systems Ethernet	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle , Advanced Driv	id vehicles /brid vehicles, architec /brid vehicles, architec Electronic vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System	Electromagnet System, Security in the Internet of (ADAS) and Aut	/, major type tic Compat , Warning S of Things, E	s of traction motor ibility, Electron ystem, infotainme nergy Manageme	ic nt nt	
	Basic of battery s Trends = Electron Dashboa and Tele Systems Ethernet Tutoria	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System / Autonomous Vehicle	Electromagnet System, Security in the Internet of (ADAS) and Autors.	/, major type tic Compar , Warning Sy of Things, E tonomous Ve	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
	Basic of battery s Trends t Electrom Dashboa and Tele Systems Ethernet Tutorial 1.	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage collection of va	id vehicles vbrid vehicles, architec Electronic vehicles erence Suppression, Onboard Diagnostic S e System of Systems ver Assistance System I Autonomous Vehicle rious sensor and actu	Electromagnet Electromagnet System, Security, in the Internet of (ADAS) and Au-	/, major type tic Compar , Warning Sy of Things, E tonomous Ve	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
	Basic of battery s Trends Electron Dashboa and Tele Systems Ethernet Tutoria 1. 2.	f EV and Hybr electrical and hy ystems. in Automotive agnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage collection of va visit to automo	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System / Autonomous Vehicle // and actures // and actures for the sensor actual sen	Electromagnet System, Security, in the Internet of (ADAS) and Autors s.	<i>I</i> , major type tic Compat , Warning S of Things, E tonomous Vo its operatio	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
	Basic of battery s Trends : Electron Dashboa and Tele Systems Ethernet Tutorial 1. 2. 3.	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage collection of va visit to automotivisit to automoti	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /er Assistance System / Autonomous Vehicle // Autonomous Vehicle // Autonomous Vehicle // Autonomous Vehicle // Autonomous Vehicle // Autonomous Vehicle // Autonomous Vehicle	Electromagnet System, Security in the Internet of (ADAS) and Autors s. ators verifying ing company curing company	<i>I</i> , major type tic Compat , Warning S of Things, E tonomous Vo its operatio	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
	Basic of battery s Trends Electrom Dashboa and Tele Systems Ethernet Tutorial 1. 2. 3. 4.	f EV and Hybr electrical and hy ystems. in Automotive agnetic interf rd Instruments, ematics, Vehicle , Advanced Driv , Connected and coverage collection of va visit to automotive energy calculat	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System l Autonomous Vehicle // Autonomous Vehicle // and actur // tive vehicle manufactur // tive vehicle manufactur // final batteries req	Electromagnet System, Security in the Internet of (ADAS) and Autors s. ators verifying ing company curing company	<i>I</i> , major type tic Compat , Warning S of Things, E tonomous Vo its operatio	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
Unit 5	Basic of battery s Trends Electron Dashboa and Tele Systems Ethernet Tutorial 1. 2. 3. 4. 5.	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage collection of va visit to automotivisit to automoti	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System l Autonomous Vehicle // Autonomous Vehicle // and actur // tive vehicle manufactur // tive vehicle manufactur // final batteries req	Electromagnet System, Security in the Internet of (ADAS) and Autors s. ators verifying ing company curing company	<i>I</i> , major type tic Compat , Warning S of Things, E tonomous Vo its operatio	s of traction motor tibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti	ic nt nt	
Unit 5	Basic of battery s Trends Electron Dashboa and Tele Systems Ethernet 1. 2. 3. 4. 5. 8 Books	f EV and Hybr electrical and hy ystems. in Automotive magnetic interf rd Instruments, ematics, Vehicle Advanced Driv , Connected and coverage collection of va visit to automot energy calculat security contro	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /er Assistance System / Autonomous Vehicle // Autonomo	Electromagnet System, Security in the Internet of (ADAS) and Autors s. attors verifying ing company curing company uirements	/, major type tic Compar , Warning S of Things, E tonomous Vo its operatio	s of traction motor ibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti nal details	ic nt nt ve	5
Unit 5	Basic of battery s Electron Dashboa and Tele Systems Ethernet Tutoria 1. 2. 3. 4. 5. 5 Books Robert Bo	f EV and Hybr electrical and hy ystems. in Automotive agnetic interf rd Instruments, ematics, Vehicle , Advanced Driv , Connected and coverage collection of va visit to automotivisit to automotivisit to automotivisit energy calculat security contro	id vehicles /brid vehicles, architec /brid vehicles, architec /brid vehicles /erence Suppression, Onboard Diagnostic S /e System of Systems /er Assistance System l Autonomous Vehicle // Autonomous Vehicle // and actur // tive vehicle manufactur // tive vehicle manufactur // final batteries req	Electromagnet System, Security, in the Internet of (ADAS) and Autors ators verifying ing company turing company uirements	/, major type tic Compat , Warning S of Things, E tonomous Vo its operatio	s of traction motor ibility, Electron ystem, infotainme nergy Manageme ehicles, Automoti nal details	ic nt nt ve	5

3.	W. Hillier and David R. Rogers, "Hillier's Fundamentals of Mo	otor Vehicle	Technology, Book 3 - Cha	ssis and
	Body Electronics", Fifth Edition, Nelson Thornes Ltd, 2007.			
		-		
Refe	rence Books			
1.	Hybrid electric vehicles. 2. Fuel cells. I. Ehsani, Mehrdad. II.	Title. III. Se	eries.	
2.	William B. Ribbens, Understanding Automotive Electronics, 6t	h Edition, E	Elsevier Publishing.	
Usefu	ıl Links			
1.	https://www.ti.com/applications/automotive/overview.html			
2.	https://www.udemy.com/topic/automobile-engineering/			
2.	https://www.udemy.com/topic/udtomobile/engineering/			

$\begin{array}{c} PO \\ \rightarrow \\ CO \\ \downarrow \end{array}$	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO 1	PSO 2	PSO 3
CO 1	2	2	2	-	1								2	-	2
CO2	2	3	2	-	2								2	-	1
CO 3	3	2	-	2	-								-	1	-
CO 4	3	2	2	-	1								2	-	1
CO 5	2	-	1	-	-								2	-	-
CO 6	2	-	1	-	1								2	-	-
total	14	9	8	2	5	-	-	-	-	-	-	-	10	1	4
Avg	2.3	2.25	1.6	1	1.25	-	-	-	-	-	-	-	1.6	1	1.33
%	76.6	75	53.3	33.3	41.6	-	-	-	-	-	-	-	53.3	33.3	43.3

Knowledge Level	CT1	CT2	TA	ESE
Remember				05
Understand	5	5	5	30
Apply	5			10
Analyze	5	5	5	10
Evaluate		5		05
Create				
TOTAL	15	15	10	60

Final Year (Semester – VII) B. Tech. Electronics and Telecommunication	
EX2755:4G/5G Communication Technology	
Teaching Scheme Examination Scheme	
Lectures02 Hrs/weekCT – 115	
Tutorials01 Hrs/weekCT - 215	
Total Credits03TA10	
ESE 60	
Duration of ESE 02 Hrs 30	0 Min
Course Outcomes (CO)	
Student will be able to	
	L2
	L5 L4
	L4 L2
	L2 L2
	L2 L6
	Hours
Unit 1 Wireless Fundamentals:	04
Cellular concept, Broadband wireless channel (BWC), Fading in BWC, Modeling BWC Empirical	04
and Statistical models, Mitigation of Narrow band and Broadband Fading	
Unit 2 Multicarrier Modulation::	07
OFDM basics, OFDM in LTE, Timing and Frequency Synchronization, PAR, SC-FDE, OFDMA	
and SC-FDMA: OFDM with FDMA, TDMA, CDMA, OFDMA, SC-FDMA, OFDMA and SC-	
FDMA in LTE	
Multiple Antenna Transmission and Reception: Spatial Diversity overview, Receive Diversity,	
Transmit Diversity, Interference cancellation and signal enhancement, Spatial Multiplexing, Choice between Diversity, Interference suppression and Spatial Multiplexing	
Unit 3 LTE(Long Term Evolution) Architecture:	09
Introduction to LTE, Channel Structure of LTE, Downlink OFDMA Radio Resource, Uplink SC-	07
FDMA Radio Resource.	
Radio Resource Management and Mobility Management: PDCP overview, MAC/RLC	
overview, RRC overview, Mobility Management, Intercell Interference Coordination	
Unit 4 5G Network Architecture:	05
Design principles and network topologies, C-RAN and V-RAN architectures and disaggregated	
base station model SDN/NFV/MEC, Network slicing, Reference architectures, and Network entities and interfaces.	
Unit 5 New Radio Access Layer 2 and Layer 3 Aspects and System Operation:	05
Our S New Kaulo Access Layer 2 and Layer 5 Aspects and System Operation: Overview of layer 2 and layer 3 functions, Layer 2 functions and services, Layer 3 functions and	03
services, UE states and state transitions, Scheduling and RRM, DRX and power saving modes,	
Mobility management, handover and UE measurements, Random-access procedure, Multi-	
connectivity, and Carrier aggregation, 5G Protocol Stack in aspect of 5G Layer 1, 5G Layer 2,	
5G Layer 3	
Note:	
Tutorials should be on following topics:	
- 4G technologies as on web-based communications.	
- Application of 4G as Multimode Software and Video Network Coding for 4G Wireless	
networks	
- 5G architecture in aspects of Internet of Things and Vehicle to Everything (V2X)	
Communications.	
- Students will create report and presentation on recent trends on real time application and issues in mobile communication.	
 Network Access Security in 5G Mobile Networks. 	
 Network Access Security in 5G Wobie Networks. Practical base study on throughput changes while going 4G to 5G and carrier aggregation. 	
Text Books	
	-).
	s <i>j</i> .
Pearson 2 Same Almosti #5C ND Analite transformer Tradicities Include and Operation of 2CDD New Dedia	
2. Sassan Ahmadi, "5G NR, Architecture, Technology, Implementation, and Operation of 3GPP New Radio	
 Standards", 1st Edition, Academic Press, 15th June 2019 3. Kan Zheng, Wei Xiang, Xuemin (Sherman) Shen," 5G Mobile Communications", first edition, springer, 2016. 	

Reference Books

1.	Erik Dahlman, Stefan Parkvall ,Johan Skold "4G: LTE/LTE-Advanced for Mobile Broadband," 2nd Ed., Elsevier,
	2014
2.	Harri Holma and Antti Toskala, "_LTE for UMTS Evolution to LTE-Advanced', Second Edition - 2011, John Wiley
	& Sons, Ltd.
3.	Afif Osseiran, Jose F. Monserrat, Patrick Marsch, "5G Mobile and Wireless Communications Technology", first
	edition, Cambridge University Press, 2016.
Use	ful Links
1.	IIT Kanpur: https://nptel.ac.in/courses/117/104/117104099/
2	https://www.angle.com/ang

2. https://www.coursera.org/lecture/smart-device-mobile-emerging-technologies/4-7-5g-architecture-6KzD8

- 3. https://www.udemy.com/course/5g-4g-lte-3g-2g-cellular-mobile-communications-wireless/
- 4. https://www.udemy.com/course/5g-networks-security-architecture-and-procedures-5g-training/

Assignments and Tutorial will be based on:

- 1. Study and discussion on Application of 4G and 5G technology in recent trends.
- 2. Solving analytical design of development issues.
- 3. Frequency spectrum allocation and utilization in terms 4G and 5G Technology
- 4. Developing real time mini project on related technology
- 5. Advancement of existing technology in mobile communication
- 6. Presentation and evaluation of projects on recent mobile communication techniques.
- 7. Review on Literature collection of advance mobile communication.
- 8. Use of different software and hardware tools for study of advance mobile communication.

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	1	1	1	1	-	-	-	-	-	-	-	-	2	-
CO 2	3	1	1	1	1	-	-	-	-	-	-	-	-	2	-
CO 3	2	2	2	1	1	-	-	1	-	-	-	-	-	2	1
CO 4	2	2	2	2	1	-	-	1	-	-	-	-	-	2	1
CO 5	2	1	1	1	1	-	-	1	-	-	-	-	-	2	1
CO 6	2	2	2	2	1	-	-	1	2	2	-	1	-	2	1
	14	9	9	9	6	-	-	-	2	2	-	1	-	12	4
	2.33	1.5	1.5	1.5	1	-	-	-	2	2	-	1	-	2	1
%	77.66	50	50	50	33.33	-	-	-	66.66	66.66	-	33.33	-	66.66	33.33
1 – Low	l – Low 2 – Medium3 – High														

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	05	-	-	05
Understand	05	-	-	10
Apply	05	-	-	10
Analyze	-	05	05	15
Evaluate	-	05	05	15
Create	-	05	-	05
TOTAL	15	15	10	60

			Government College				
		Final Year	(Semester – VII) B. Tech	. Electronics and Te ech Processing	lecommunication		
Tor	aching	Scheme	EA2/10. Spec	een riocessing	Examination Sch	0000	
	ctures	02 Hrs./week			CT – 1	15	
	torials	02 His./week			CT = 1 CT = 2	15	
	tal Crec		•		TA	10	
10					ESE	60	
					Duration of ESE	02 Hrs	20 Min
Co		utcomes (CO)			Duration of ESE	02 1118	50 WIIII
		ill be able to					
			of speech and speech produce	tion avatam			1.2
-			of speech and speech produc				L2 L5
			parameters/features for speech				
			Linear Prediction Coefficien		t approaches.		L3
			techniques for representing s	peech.			L2
			synthesis techniques.	•			L4
6.	Create	report and presenta	tion on recent trends in speech				L6
-	T •4 4			Contents		1 0	Hours
ι	J nit 1		tals: Review of Digital Sign				(08)
			culatory phonetics, acoustic			oduction,	
т	T .4 0		for speech production, Ear p				(00)
ι	Jnit 2		Short Time energy, average r				(08)
			rt-time autocorrelation, pitch tion based on FFT and harmonic				
			, evaluation of formants using				
			Coefficients (MFCC)	g Cepstrum, Homomor	plife Speech I locess	ing, wiei	
Т	Jnit 3		of Speech: Review of lattic	ce structure realization	Forward Linear Pr	ediction	(06)
Ľ	Jint 5		es for finding LPC-Autoco				(00)
τ	J nit 4	Prediction based V Prediction, Sinusoid Text to speech sys	d Synthesis: Parametric Spe Vocoders, Residual Excited, dal Speech Coding, Mixed Ex tem (TTS), Synthesizer Tech hesis, Sine-wave synthesis	Voice Excited, Multi acitation Linear Predict	Pulse, Code Excite	d Linear	(08)
		as - Praat, Wave sur	will be based on Speech & A fer, HTK, Cool edit, MATLA	B etc. Different Audio	standards such as MI	P3, MP4,	
			file formats. Students should h Recognition(ASR), Speech				
			beech for human assistance- a			ognition	
Тет	xt Bool		seen for numan assistance- a				
			ital Processing of Speech Sig	nals" Pearson Education	n Delhi 2004		
			nd Audio Processing", Wiley				
			"Speech Communications: H			vderahad	Secon
	•	n, 2001.	Speech communications. In	annan a machine, c		Jaoradad	,
		e Books				<u> </u>	
			ete-Time Speech Signal Proc	essing – Principles and	Practice" Pearson	Education	1 2002
			alysis Synthesis and Percept				., 2002.
			gan, "Speech and audio signa				nd music
-•	•	- India Edition, Stud		, processing , processing	no una perception or	Specch di	
Use	eful Li		Do ition, 2000.			[
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2.	<u> </u>	· · · · · · · · · · · · · · · · · · ·	watch?v=X JvfZiGEek&list	=rl9003926/A92313	<u>/ U</u>		
		· · · · · · · · · · · · · · · · · · ·	watch?v=GxkzxTFvhDU				
4.	-		aculty/Rabiner/ece259/speec	h%20course.html			
5.	-	/www.youtube.com/					
6.	Ihttne./	/www.voutube.com/	watch?v=cnkVeKtaTjk&t=1	660s			

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	1	1	-	-	-	-	-	-	-	-	-	-	-
CO 2	3	2	2	1	1	-	-	-	-	-	-	-	-	2	-
CO 3	2	2	2	1	1	-	-	-	-	-	-	-	-	-	-
CO 4	2	2	-	1	1	-	-	-	-	-	-	-	-	2	-
CO 5	2	2	1	1	1	-	-	-	-	-	-	-	-	2	1
CO 6	2	2	2	2	2	-	-	-	2	2	-	1	1	2	1
AVG	2.33	2	1.6	1.16	1.2	-	-	-	2	2	-	1	1	2	1
%	77.77	66.66	53.33	38.88	40.00	-	-	-	66.66	66.66	-	33.33	33.33	66.66	33.33

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	-	-	-	-
Understand	04	05	-	10
Apply	05	05	03	20
Analyze	03	05	02	20
Evaluate	03	-	02	10
Create	-	-	03	-
TOTAL	15	15	10	60

		Government Colle	ege of Enginee	ring, Kara	d		
	Final Year (Semester – VII) B. T	ech. Electronio	cs and Tel			
		EX2726: Bi	g Data and Dat	ta Mining	r		
Teaching Sche					Examination Sch	r	
Lectures	02 Hrs/week				CT - 1	15	
Tutorials	01 Hrs/week				CT – 2 TA	15	
Total Credits	03				ESE	10 60	
					Duration of ESE	00 Hrs	30 Min
Course Outcor	nes (CO)				Durution of LDL	021115	50 IVIII
Student will be							
1. Explain the	Data Mining fu	undamentals					L2
		R programming and Pyt					L3
		ation and Clustering te		ysis.			L5
		s of Big Data and its te					L2
	*	cept in distributed data					L3 L6
0. Create repo	rts and Presenta	ation on recent trends in	irse Contents				Hours
Unit 1 Introd	uction to Big I		irse Contents				5
Introd	luction to big d	ata: Data, Characteristi					J
		Structured, Sources of				on and	
Defin	ition of big data	a, Characteristics and N big data environment	leed of big data	, Challenge	s of big data, Data		
	Reduce Program						5
		educe, Processing data	with Hadoop usi	ng MapRed	uce. Introduction to	YARN.	5
		l Challenges of YARN,				,	
	ication and Pro						6
		d Prediction Concepts.	Maggung Tree	Danina			
		tion: Attribute Selection ion: Naïve Bayes" Class		Pruning			
		n-Linear Regression, Ot		Based metho	ds.		
		n: Accuracy and Error n				ng, Cross	
		Comparing Classifier pe	erformance using	g ROC Curv	es.		5
	r Analysis : Concepts Types	of Data in Cluster Anal	vsis				5
	ew of basic clus		<i>y</i> 515.				
		K-Means, K-Mediods.					
	chical Methods:						
	y-Based Method Mining:	IS: DBSCAN					5
		what kind of Data, Kin	d of patterns to b	e mined.			5
		Mining, Data Preprocess			ta, Descriptive Data	l	
		Cleaning, Data integrat					
		te following task durin	0	Hours.			
•		g different Hadoop mod ementation of file mana					
•		on of Matrix Multiplica		o Map Redu	ce,		
•	Run a Map R	educe program to under					
•	Pi Spark	an af V		1			
•		on of K-means clusterin essing tasks and	g using Map Rec	luce			
		ule mining on data sets					
•	Classification	on data sets					
•	Clustering on	data sets.			r		
Text Books	"Dete Mini	Concents and Tester'	North Margan IZ	ufman 2	d Edition		
		g Concepts and Techniq	C				
		Bruce, "Data Mining f			ncepts, Techniques,	and App	lications
		vith XLMiner", 1 st Edit					
		Editorial services, Drean Chellappan, "Big Data			cations First Edition	2015	
4. Seema Acna Reference Boo		Chenappan, Big Dala	and Analytics, V		cations, Flist Edition	1,2013	
		/ipin Kumar, "Introduct	ion to Data Mini	ng", Pearson	n Education		
		Linoff "Data Mining T		-			
	•	8	1 /		-		

3.	Hadoop: The Definitive Guide, Tom White, Third Edition, O'Reilley, 2012.								
Use	ful Links								
1.	1. https://www.coursera.org/specializations/big-data								
2.	2. http://index-of.co.uk/Big-Data- Technologies/Data%20Science%20and%20Big%20Data%20Analytics.pdf								
3.	3. https://nptel.ac.in/courses/106105174/								

4. https://www.coursera.org/specializations/big-data

Mapping of COs and POs

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	1	1	1								2	-	1
CO2	2	1	2	2	2								2	-	2
CO 3	3	2	2	2	-								2	-	-
CO 4	2	-	1	1	-								2	-	-
CO 5	3	2	2	2	2								2	-	2
CO 6	2	2	2	1	2				2	2		1	2	-	2
Total	15	9	10	9	7	0	0	0	2	2	0	1	12	0	7
Avg	2.5	1.8	1.7	1.5	1.75	0	0	0	2	2	0	1	2	0	1.75
%	83.3	60.0	55.6	50.0	58.3	0.0	0.0	0.0	66.7	66.7	0.0	33.3	66.7	0.0	58.3

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	5			5
Understand		5	2	10
Apply	5	5	2	15
Analyze			2	10
Evaluate		5	2	10
Create	5		2	10
TOTAL	15	15	10	60

		Government College of	Engineering, Kara	d		
	Final Year (S	Semester – VII) B. Tech. E				
		EX2736: RF IC Designing	ng			
Teachin	g Scheme			Examination Sch	eme	
Lectures				CT – 1	15	
Tutorials	s 01 Hrs/week			CT – 2	15	
Total Cr	edits 03			ТА	10	
				ESE	60	
				Duration of ESE	02 Hrs	30 Min
	Outcomes (CO)					
	will be able to					
		MOSFETs, BJTs and CMOS.				L4
		rmer, BALUN, mixers, induct		etc.		L3
		occurs during the RF IC design	ning.			L4
	elop various amplifier c					L3
•	lain the various Archite		·			L2
6. Crea	ate report and presentati	on on one example of RF IC d	esign.			L6
•		Course Co				Hours
Unit 1		IC compared to MMIC, RF n				5
		sses, substrate isolation using				
		hip inductors and MIM capa	citors and modelling	, Transmission Lir	nes and	
TI:4 0	distributed component	<u>s</u> se of VCOs, Two-port oscilla	ton mothed to model	mhaca naica. Cilha	et Call	_
Unit 2		UN, Lumped BALUN, On-chi				5
	Mixer operation and d		p Transformer, Water		nature	
Unit 3	Â.	Source of Noise-Flicker Noise	e. Shot Noise. Therma	l Noise, Burst Noise	. Noise	6
cint c		ain Stages, Ferris Formula, N				Ū
	topologies-Cascade an	d Cascade		C		
Unit 4		of Power Amplifier in Comm				6
		rn Loss, Linearity, ACPR and	I ACLR, TOI, Error V	ector Magnitude, C	Class of	
TT •4 🖻	PAs- A, B, C, AB, D,			Tanana ittaa aa 1 D	· · · ·	
Unit 5		ures- Heterodyne, Direct Co er/ Noise Figure/ Linearity Bu		Transmitter and R	eceiver	6
NI-4-		• •	0 0		A L LINI	
Note		l on implementation of RF n citors, transformers, power				
		oftware Magic VLSI (mentior				
	target specification.	ortware magic v Loi (mentior	100 III useful IIIKs (3)	, ioi physical design	i as per	
	anger speenreution.					
Text Boo	ks					
		RFIC and MMIC Design and	Technology (Materia	als, Circuits and Dev	vices) 2n	d Edition
Reference		*				
	· ·	lectronics, Prentice Hall PTR,				
		n of CMOS radio-frequency in	tegrated circuit, Camb	oridge University Pi	ress, 200	6
	ris Bowick, RF Circuit I	Design, Newnes, 2007				
Useful Li						
^	://nptel.ac.in/courses/11					
	://designers-guide.org/d					
3. <u>http:</u> /	//www.ee.iitm.ac.in/~an	i/2011/ee6240/lectures.html				
4. http:/	//www.nptelvideos.in/20)12/12/rf-integrated-circuits.ht	ml			
5. http:/	//www.hp.woodshot.com	<u>n/</u>				

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	2	1										3		
CO2	3	2	1	1	2							1	3		2
CO 3	2	2	2	1	2							1	3		1
CO 4	2	2	2	1	2								2		1
CO 5	1	1			1								1		
CO 6	2	2	1		2				2	2		2			
avg	2	1.833	1.16	0.5	1.5				0.33	0.33		0.66	2		0.66
%	66.66	61.11	38.88	16.66	50				11.11	11.11		22.22	66.66		22.22

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				
Understand	10			10
Apply	5	10		10
Analyze		5	3	20
Evaluate			3	20
Create			4	
TOTAL	15	15	10	60

				e of Engineering, Kara			
		Final Year (h. Electronics and Tele			
			EX2746: Elective I	V- Medical Electronics			
Teachin	0				Examination Sch		
Lectures		02 Hrs/week			CT - 1 CT - 2	15	
Tutorial Total Cr		01 Hrs/week 03			$\frac{CI-2}{TA}$	15 10	
Total CI	ealts	05			ESE	60	
					Duration of ESE	02 Hrs	30 Min
Course	Outcon	nes (CO)			Durution of LOL	02 1115	50 Willi
Student							
1. Sum	marize	usage of electro	nics in medical field.				L1
		•		ar, Blood pressure with ad	vanaa taahniguaa		L1 L2
			is for health monitoring.	a, blood pressure with ad	vance techniques.		L2 L3
			s, DC Defibrillator, Radio	Pill and Telestimulation			L5 L5
			mputed Tomography.				L5 L6
				d expert systems for hospi	tals		L3
01 010			00	e Contents			
	Floctre	Dhysiology f	ndamentals And Bio-Po				Hours 7
Unit 1		• 0•		ns of Body, Sourses of	RioMadical Sime	la Docia	1
Cint I		• •		•	Ũ		
	Medica			f Biopotentials, Bio Pot		-	
	-		• • •	encephalography (EEG),	Electromyography	(EMG),	
), Phonocardiogram (PCC				
TI:4 0			n Electrical Parameter M				7
Unit 2			· •	neter, Photometer, Autoa	•		
			-	mperature Measurement,	Pulse Measurement	t, Blood	
			ugar Measurement, Blood	l Pressure Measurement .			
			elemetry and Safety :				4
Unit 3			OC Defibrillator, Telemet	ry Principles & Bio Telem	etry, Radio Pill An	d	
		mulation , · Electrical Safe	ty In Modical Equipment	Cyber Security in Medical	Dovices Demote I	Dotiont	
	-		atient data and Profile ma	•	i Devices, Remote i	attent	
		ogical Equipm		inagement systems.			6
Unit 4				Of Radio Isotope In Diagn	osis Padiation The	ropy V	U
Omt 4		0		1 0		1.5	
	-	-		Computed Tomography,	Standards and prac	tices for	
			evices / equipment,	a .			
Unit 5		e e	Scanning and Imaging	•			4
omt 5				Magnetic Resonance Ima			
		001	stems for measurement of	Bone Density, Fetal diag	nosis, Thermal Ima	ging	
	System				• •		
NI-4-				ring systems and Patholog		•	
Note:	-			ardiology equipments, Th			
			•	Medical expert systems	for hospitals, Mee	dical	
		re, m-health, c-	Health – Medical Informa	tics.			
Text Bo							
				ment Design and Develo	pment from Requi	rement to) Marke
		', Wiley Publica			Dronting hall ft. 1	NI	Na11-1
				easurement", 2nd edition,			
	5555379		insu unientation Applicatio	on and Design", Wiley Ind	uia, routui Dattion,	19011 13	. 7/0-
Referen							
		1317		I			
1. R. S.	. Khand	pur, "Bio Med	ical Instrumentation Techr	nology and Applications "	, Tata McGraw Hill	Publicati	on, .
repri	nt .	-					
			dical Instrumentation and	Measurements", PHI lear	ning Pvt. Ltd. ISBN	V 13: 978-	-
)342279			4 4 4 7 7 1			
3. Jose	ph D. B	ronzıno,I The bi	omedical engineering han	dbook", Volume 1 & 2, Cl	RC Press, USA, 200)0.	

Use	eful Links								
1.	1. https://www.goodreads.com/book/show/6089646-biomedical-instrumentation								
2.	https://dadanbav.web.app/r-s-khandpur-fkel9.html								
3.	3. https://www.journals.elsevier.com/biosensors-and-bioelectronics								

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	1	-	2	-	-	-	-	-	-	-	2	-	-
CO2	2	1	1	-	2	-	-	-	-	-	-	-	1	-	1
CO 3	2	2	2	-	2	-	-	-	-	-	-	-	2	1	2
CO 4	2	-	1	-	1	-	-	-	-	-	-	-	1	-	-
CO 5	2	-	1	-	1	-	-	-	-	-	-	-	1	-	1
CO 6	2	1	1	-	1	-	-	-	2	2	-	1	2	-	1
total	13	6	7	-	9	-	-	-	2	2	-	1	9	1	5
Avg	2.1	1.5	1.16	-	1.5	-	-	-	1	1	-	1	1.5	1	1.25
%	70	50	83.66	-	50	-	-	-	33.33	33.33	-	33.33	50	33.33	41.66

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	-	-	-	10
Understand	05	-	05	10
Apply	05	05	05	10
Analyze	05	05	-	10
Evaluate	-	05	-	10
Create	-	-	-	10
TOTAL	15	15	10	60

Final Year (Semester – VII) B. Tech. Electronics and Telecommunication EX2756- Radar Engineering Teaching Scheme Lectures 00 Hrs./week CT – 1 15 Tatorials 01 Hrs./week CT – 2 15 Total Credits 03 TA 10 Total Credits 03 TA 10 Course Outcomes (CO) Student will be able to 1 Illustrate the fundamentals of Radar systems. L2 2. Solve problems on radar equations. C/W and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW.JPM.MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for spresific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Unit 1 Introduction to Radar:-Basics of Radar, Radar equation. Block Diagram, Radar Frequencies. (09) 12 CW and Frequency-Modulated Radar:- Introduction to Doppler and MTI radar. NUT radar Block diagram. (08) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and rabes adam: Simple, complex Targets, Pulse Repetition Frequency CW Radar (09)			Government College of	Engineer	ring, Kara	d				
Teaching Scheme Examination Scheme Lectures 02 Hrs/week CT - 1 15 Tutorials 01 Hrs/week CT - 2 15 Total Credits 03 TA 10 ESE 60 Duration of ESE 02 Hrs 30 Min Course Outcomes (CO) Student will be able to 1 1.2 1 Illustrate the fundamentals of Radar systems. L2 Solve problems on radar equations, CW and Pulsed Radar, Tracking Radar 1.3 3. Analyze the working principle of CW.FM,MT1 and Pulse Doppler Radar 1.4 Evaluate different types of radars for specific applications. 1.5 5. Create report and presentation on recent trends in modern radar systems. 1.6 Hours Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies. 100 9 Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Trequency. CW Radar (08) Unit 2 CW and Frequency-Modulated Radar:- Introduction to Doppler and MT1 radar, MT1 radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) radar, Search and Tracking Radar:- Students should prepare report and presentation on Emerging and Modern Applications o		Final Year (<u> </u>	<u> </u>	0,		n			
Lectures 02 Hrs./week CT - 1 15 Tutorials 01 Hrs./week CT - 2 15 Total Credits 03 TA 10 Course Outcomes (CO) ESE 60 Duration of ESE 02 Hrs. 30 Min Student will be able to Illustrate the fundamentals of Radar systems. L2 2 2. Solve problems on radar equations. CW and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for specific applications. L5 Center report and presentation on recent trends in modern radar systems. L6 Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, U99 U9 Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency W Radar (08) Unit 2 CW and Frequency-Modulated Radar:- Doppler offect, Simple CW Doppler radar, Frequency-Modulated CW Radar Tracking Radar. Students should prepare uport and presentation on Emerging and Miltiple-Frequency of Radar. (07) (08) unit 3 MTI and Pulse Doppler Radar. Students should prepare report and presentation on Emerging and Midar, Sardra Miltiple-Frequency CW Radar (10) Radar, Search and Tracking Rada			EX2756- Radar	Engineer	ring					
Tutorials 01 Hrs./week CT - 2 15 Total Credits 03 TA 10 ESE 60 Duration of ESE 02 Hrs 30 Min Course Outcomes (CO) Student will be able to 1. Illustrate the fundamentals of Radar systems. 1.2 Student will be able to 1.3 Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar 1.4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies. (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarn: Simple, complex Targets, Pulse Repetition Frequency (08) Unit 2 CW and Frequency-Modulated Radar: - Doppler refect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (07) radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Radar, Search and Tracking Radar. Students should prepare report and presentation an Engring and Modern Applications of Radar Systems, Tata McGr	Teaching Sch	eme			U	Examination S	cheme			
Total Credits 03 TA 10 ESE 60 Duration of ESE 02 Hrs 30 Min Course Outcomes (CO) Duration of ESE 02 Hrs 30 Min Course Outcomes (CO) Student will be able to 1 Illustrate the fundamentals of Radar systems. L2 Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 Evaluate different types of radars for specific applications. L5 Solve problems on recent trends in modern radar systems. L6 Course Contents Hours Unit 1 Introduction to Radar: Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MT1 and Pulse Doppler Radar: - Introduction to Doppler nadar (08) modulated, CW Radar, Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Tat Arget Reflection Characteristics and Angul	_					CT – 1	15			
ESE 60 Ouration of ESE 02 Hrs 30 Min Student will be able to 02 Hrs 30 Min Illustrate the fundamentals of Radar systems. L2 Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Ourse Contents Hours Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies. (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarn:: Simple, complex Targets, Pulse Repetition Frequency (08) Unit 2 CW and Frequency-Modulated Radar: - Doppler radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar, MTI radar block diagram, CW and radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, Sevens and Signal-to-noise Radar, CW and Pulsed Radar, Scarch and Tracking Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Text Books	Tutorials	01 Hrs./week				CT – 2	15			
Course Outcomes (CO) Duration of ESE 02 Hrs 30 Min Student will be able to 1 Illustrate the fundamentals of Radar systems. L2 Solve problems on radar equations .CW and Pulsed Radar, Tracking Radar L3 Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 Évaluate different types of radars for specific applications. L5 Create report and presentation on recent trends in modern radar systems. L6 Course Contents Hours Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, modulated CW Radar, Toroben Doppler Radar:-Doppler radar, Frequency-modulated CW Radar, Toroben Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 2 CW and Frequency-Modulated Radar:- Introduction to Doppler radar (07) radar, Taracking Radar- Tracking Radar report and presentation on Emerging and Modern Applications of Radar Students should prepare report and presentation on Emerging and Modern Applications of Radar Students should prepare report and presentation on Emerging and Modern Applications of Radar report and reaking Radar Tracking Radar: Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Radar, Scarch and Tracking Radar Students should prepare report and presentation on E	Total Credits	03				ТА	10			
Course Outcomes (CO) Student will be able to 1 Illustrate the fundamentals of Radar systems. L2 2. Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Course Contents Hours Outcomes (09) Potection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarn: Simple, complex Targets, Pulse Repetition Frequency (08) Outcomes And Frequency-Modulated Radar:- Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar Outple and Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, CW and Pulsed Radar Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, andysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Cet						ESE	60			
Student will be able to 1. Illustrate the fundamentals of Radar systems. L2 Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Modern types of radars for specific applications. Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies. Mount 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequency-modulated Radar:-Doppler Tadar, Prequency-Modulated Radar:-Doppler frequency (08) Unit 1 Introduction to Doppler Radar:-Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (08) Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, CW and Pulsed Radar, Sequential lobing and Conical scan, Mono-pulse tracking and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Text Books 1 Meril Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition [1] 2. <td></td> <td></td> <td></td> <td></td> <td></td> <td>Duration of ESE</td> <td>E 02 Hrs</td> <td>30 Min</td>						Duration of ESE	E 02 Hrs	30 Min		
1. Illustrate the fundamentals of Radar systems. L2 2. Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 1. Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) 0. Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) 0. Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency CW Radar (08) 0. Dit and Pulse Doppler Radar:- Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) 1. Taracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. </td <td>Course Outco</td> <td>omes (CO)</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>	Course Outco	omes (CO)								
2. Solve problems on radar equations ,CW and Pulsed Radar, Tracking Radar L3 3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar L4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Course Contents Hours Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (09) Unit 2 CW and Frequency-Modulated Radar:- Doppler refect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Naligation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler radar (07) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, CW and Pulsed Radar, Search and Tracking Radar: Students should prepare report and presentation on Emerging and Modern Applications of Radar Systems, Tata McGraw Hill, Third Edition 1 <td <="" colspan="2" td=""><td>Student will b</td><td>e able to</td><td></td><td></td><td></td><td></td><td></td><td></td></td>	<td>Student will b</td> <td>e able to</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>		Student will b	e able to						
3. Analyze the working principle of CW,FM,MTI and Pulse Doppler Radar 1.4 4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Mount of the types of radars for specific applications. Unit 1 Introduction to Radar: -Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) Unit 2 W and Frequency-Modulated Radar: - Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar: - Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) Variang Radar: - Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Radar, Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. 11 Introduction to Radar Systems, Tata McGraw Hill, Third Edition <	1. Illustrate t	he fundamentals o	of Radar systems.					L2		
4. Evaluate different types of radars for specific applications. L5 5. Create report and presentation on recent trends in modern radar systems. L6 Course Contents Hours Unit 1 Introduction to Radar: Basics of Radar, Radar equation, Block Diagram, Radar Frequencies. (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Delay line canceler, Moving-target-detection to Doppler adar MTI radar, MTI radar block diagram, and pelay line canceler, Moving-target-detection, Pulse Doppler radar (07) radar, arget-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. Text Books 1 1. Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition 2. G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. 3. Hovanessian, S.A., "Radar system design and analysis", Artech House 1 <	2. Solve prob	olems on radar equ	uations, CW and Pulsed Radar,	Tracking	Radar			L3		
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 5. Create report and presentation on recent trends in modern radar systems. L6 Course Contents Hours Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, (09) Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency Unit 2 CW and Frequency-Modulated Radar:- Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler and MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking (07) radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, CW and Pulsed (10) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. Text Books Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. Hovanessian, S.A., "Radar system design and analysis", Artech House Reference Books Mark A. Richards, James A. Scheer, William A. Holm, —Principles of Modern Radar, Scitech Publishing. Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. Levanon,	4. Evaluate d	ifferent types of r	adars for specific applications.					L5		
Unit 1 Introduction to Radar:-Basics of Radar, Radar equation, Block Diagram, Radar Frequencies, Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (09) Unit 2 CW and Frequency-Modulated Radar:- Doppler Rect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler nadar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Reference Books 1 Intracking Radar systems, Tata McGraw Hill, Third Edition 2 G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. 1 1 Merill Skolnik, — Introduction to Radar Systems, Scientech Publishing Inc. 2 1 1 Reference Books 1 1 1 1 1 1 <	5. Create rep	ort and presentation	on on recent trends in modern	adar syste	ems.			L6		
Detection of signal in noise, Receiver Noise and Signal-to-noise Ratio, Probability of detection and false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) Unit 2 CW and Frequency-Modulated Radar:- Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar:- Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler and MTI radar block diagram, frequency-Modulated Radar:- Tacking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Init 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking (07) (10) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. 1 I. Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition 2 G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. 1 Mereteree Bools 1 Mark A. Richards, James A. Scheer, William A. Holm, —Principles of Modern Radar, Scitech Publishing. 2 Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. 2 2 1 Mark A. Richards, M. A., "Fundamentals of R		8	Course Co	ntents				Hours		
false alarm: Simple, complex Targets, Pulse Repetition Frequency (08) Unit 2 CW and Frequency-Modulated Radar:- Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Luit 4 Tracking Radar:- Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Text Books I Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition 2 G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. 1 Mark A. Richards, James A. Scheer, William A. Holm, —Principles of Modern Radar, Scitech Publishing. 2 Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. 2 2 Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. 3 2 2 3 4 Richards, M. A., "Fundamentals of Radar Signal Proce	Unit 1 Int	roduction to Ra	dar:-Basics of Radar, Radar	equation	, Block Di	agram, Radar Fi	equencies,	(09)		
Unit 2 CW and Frequency-Modulated Radar:- Doppler effect, Simple CW Doppler radar, Frequency-modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (08) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Init 4 Tracking Radar:- Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) 1. Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition Use PVt Ltd. 2. G. S. N. Raju, —Radar system design and analysis", Artech House Implementational publishing House Pvt Ltd. 3. Hovanessian, S.A., "Radar system design and analysis", Artech House Implementational publishing. 2. Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. Implementation Radar Systems, Scientech Publishing. 3. Levanon, N., "Radar principles", John Wiley & Sons Implementation Sons Radar Systems, Scientech Publishing Inc. 3. Levanon, N., "Radar principles", John Wiley & Sons </td <td>Det</td> <td>ection of signal in</td> <td>n noise, Receiver Noise and S</td> <td>ignal-to-n</td> <td>oise Ratio,</td> <td>Probability of det</td> <td>ection and</td> <td></td>	Det	ection of signal in	n noise, Receiver Noise and S	ignal-to-n	oise Ratio,	Probability of det	ection and			
modulated CW Radar, Airborne Doppler Navigation, Multiple-Frequency CW Radar (08) Unit 3 MTI and Pulse Doppler Radar:- Introduction to Doppler and MTI radar, MTI radar block diagram, Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (07) Lunit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar, Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. 1 I. Merill Skolnik, — Introduction to Radar Systems, Tata McGraw Hill, Third Edition 2 G. S. N. Raju, —Radar Engineering and Fundamentals of Navigational Aids, I. K International publishing House Pvt Ltd. 1 J. Hovanessian, S.A., "Radar system design and analysis", Artech House 1 Reference Books 1 1 Mark A. Richards, James A. Scheer, William A. Holm, —Principles of Modern Radar, Scitech Publishing. 2 Simon Kingsley, Shaun Quegon, —Understanding Radar Systems, Scientech Publishing Inc. 3 2 <t< td=""><td>fals</td><td>e alarm: Simple, o</td><td>complex Targets, Pulse Repetit</td><td>ion Frequ</td><td>ency</td><td></td><td></td><td></td></t<>	fals	e alarm: Simple, o	complex Targets, Pulse Repetit	ion Frequ	ency					
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Delay line canceler, Moving-target-detection, Pulse Doppler radar (07) Unit 4 Tracking Radar:- Tracking with Radar, Sequential lobing and Conical scan, Mono-pulse tracking radar , Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Tutorials: Tutorials will be based on solving Problems on Basic Concepts of Radar, CW and Pulsed Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Text Books	mo	dulated CW Rada	r, Airborne Doppler Navigatio	n, Multipl	e-Frequency	y CW Radar				
radar , Target-Reflection Characteristics and Angular Accuracy, Tracking in Range (10) Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. (10) Text Books		-	-	. .		r, MTI radar bloc	k diagram,	(08)		
Radar, Search and Tracking Radar. Students should prepare report and presentation on Emerging and Modern Applications of Radar Principles. Design, simulation, analysis, and testing of radar systems can be done using MATLAB & Simulink, AWR or CAD FEKO software. Text Books							se tracking	(07)		
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Reference Books Image: Constraint of the system of the		aju, —Radar Eng	ineering and Fundamentals of I	Navigation	nal Aids, I. I	K International pu	ıblishing H	ouse Pvt.		
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3. Levanon, N., "Radar principles", John Wiley & Sons 4. Richards, M. A., "Fundamentals of Radar Signal Processing" Tata Mc-Graw hill Useful Links 1. https://nptel.ac.in/courses/108/105/108105154/ 2. http://www.ll.mit.edu/outreach/radar-introduction-radar-systems-online-course							0			
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	A			stems-onl	ine-course					
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$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	1	1	-	-	-	-	-	-	-	-	-	2	-
CO 2	3	2	2	1	-	-	-	-	-	-	-	-	-	2	-
CO 3	2	3	2	2	-	-	-	-	-	-	-	-	-	2	-
CO 4	3	2	2	2	-	-	-	-	-	-	-	-	-	2	-
CO 5	2	2	1	2	-	-	-	-	2	2	-	1	-	2	1
AVG	2.6	2.2	1.6	1.6	-	-	-	-	2	2	-	1	-	2	1
%	86.66	73.33	53.33	53.33	-	-	-	-	66.66	66.66	-	33.33	-	66.66	33.33

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	-	-	-	-
Understand	04	02	-	10
Apply	05	05	03	20
Analyze	03	05	02	20
Evaluate	03	03	02	10
Create	-	-	03	-
TOTAL	15	15	10	60

		Go	vernment College of Engineering, Karad									
	Fin	al Year (Semester –	VII) B. Tech. Electronics and Telecommunication Engineering									
			2707 : Image and Video Processing Lab									
	atory Sc		Examination Scheme									
Practic		2 Hrs/week	TA/CA 25									
Total C			ESE 25									
	Will be a	nes (CO)										
1.			s for smoothing thersholding, negation and filtering operation in Image.	L6								
2.		· · ·	als and its compression.	L6								
3.		different video Editing		L3								
4.		lifferent motion estima		L3								
			List of Experiment									
Experi	ment 1	Demonstration of Imag	ge Smoothing Operation									
Experi	ment 2	Implement RGB to Gr	ay scale Image Processing using DIPLAB-1.0 and MATLAB.									
Experi	Experiment 3 Demonstration negation of image using DIPLAB-1.0											
Experi	ment 4	Apply different thresh	olds & filters using DIPLAB-1.0 and MATLAB.									
Experi	ment 5	Demonstration of conv MATLAB.	ert between color spaces and perform filtering on color images in									
Experi			ssion using MATLAB (Experiment with compression ratio And Calculate ares on compressed images.)	;								
Experi			deo editing in MATLAB									
Experi	ment 8	Interpret how to read, p	process, and display RGB & YUV video data in MATLAB.									
Experi			t parameters of digital video signal (such as The frame rate, The line f samples per line and frame interval) and effect of their on video									
Experi			ate various video compression techniques.									
Experi	ment 11	Construct motion estir in MATLAB.	nation using the HBMA (Hierarchical block matching algorithm) method									
Experi	ment 12		ation using the Block-based motion Estimation algorithm method in									
Experi	ment 13	How to add metadata	in Image and Video									
Experi	ment 14	Study on 4K/2K Imag	e Technology									
List of Submis												
		1 Total number of E	•									
		AND TRACKING I	n Report: Open ended Project (CASE STUDY: OBJECT SEGMENTATION N THE PRESENCE OF COMPLEX BACKGROUND)									
		3										

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO ₂	PSO3
CO↓															
CO 1	3	2	2	1	3	-	-	-	2	1	-	1	1	2	1
CO 2	2	3	2	2	2	-	-	-	1	1	-	-	1	2	-
CO 3	2	2	1	1	3	-	-	-	2	1	-	1	1	2	-
CO 4	2	2	1	-	1	-	-	-	1	1	-	-	1	2	-
total	9	9	6	4	8	-	-	-	6	4	-	2	4	8	1
Avg	2.25	2.25	1.5	1.33	2	-	-	-	1.5	1	-	1	1	2	1
%	75	75	50	44.44	66.6	-	-	-	50	33.3	-	33.33	33.3	66.6	33.3

Knowledge Level	CA	ESE
Remember	-	05
Understand	-	05
Apply	05	05
Analyze	10	05
Evaluate	10	05
Create	-	-
TOTAL	25	25

		Go	vernment College of Engin	eering, Karad		
	Fina		VII) B. Tech. Electronics a		tion Engineerin	g
)8 : Fiber Optics & Optica			
	atory Sch				mination Scheme	
Practic		2 Hrs/week		TA/0		
Total C	e Outcon			ESE	25	
	Will be a					
1.		izing the basic compo	ents in fiber optics.			L2
2.		optical resources and				L4
3.		Link budget and rise				L6
4.	Develop	methodology for faul	diagnosis in fiber optical netw			L4
			List of Expe			
Experi	iment 1	Demonstration of fibe	optics components and visit to	o installation optical fi	ber network	
Experi	iment 2	Measurement of Num	erical aperture			
Experi	iment 3	Determine the V-I Ar	P-I Characteristics of Laser S	ource		
Experi	iment 4	Characterization of C	culator Add - Drop of Wavele	ngth in a CWDM link		
Experi	iment 5	Implementation of Ba	kward Pumping in Erbium Do	ped Fiber Amplifier		
Experi	iment 6	Measurement of Smal	Signal Gain and Saturation O	utput Power in EDFA		
Experi	iment 7	Calculation of Rise ti	ne budget & Link Power Budge	et		
Experi	iment 8	Identification and me	surement of faults in Single mo	ode optical Fiber using	OTDR	
Experi	iment 9	Characterization of F	ber Bragg Grating (FBG)			
Experi	iment 10	Analyze the PC to PC	Communication using fiber lin	k		
Experi	iment 11	Illustrate four Channe	Course Wavelength Division	Multiplexing / De-Mul	tiplexing	
Experi	iment 12	Determine the Optica	Cross Talk in Adjacent Chann	els		
List of Submi						
		1 Total number of H	xperiments: 10			
		2 Field Visit Report	01			

mappin		Jo unu													
$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	1	2	1	1	-	-	-	2	-	-	-	-	2	1
CO 2	3	1	2	1	2	-	-	-	2	-	1	-	-	2	2
CO 3	3	1	2	2	-	-	-	-	2	1	-	-	-	2	1
CO 4	3	1	2	1	3	1	-	-	2	1	-	1	-	2	1
	12	4	8	5	6	1	0	0	8	2	0	1	0	8	5
	3	1	2	1.25	2	1	0	0	2	1	0	1	0	2	1.25
%	100	33.33	66.66	41.66	66.66	33.33	0	0	66.66	33.33	0	33.33	0	66.66	41.66
1 – Low	1 – Low 2 – Medium3 – High														

Knowledge Level	CA	ESE
Remember	-	05
Understand	-	05
Apply	05	05
Analyze	10	05
Evaluate	10	05
Create	-	-
TOTAL	25	25

	Go	vernment College of Engineering, Karad	
Final		- VII) B. Tech. Electronics and Telecommunication Engineer	ring
		EX2709: Industrial Training	
Laboratory Sche		Examination Schen	
Practical	2 Hrs/week	CA 2	
Total Credits	1	ESE 2.	5
Course Outcome	· · · · ·		
tudent Will be abl			
		arious departments in the industry.	L2
		in academics to the industry.	L3
		trial environment & its impact in societal, environmental contexts	-
		earning techniques, resources, and modern engineering tools.	L6
5. Assess pro	fessional ethics &	*	L5
		Course Contents	
2.	 and allied He / she w students h before eva will be con report and Report is measuring organization documenta gauges use departmen procedures Quantum both. 	referably dealing with Electronics & Telecommunication Engineering discipline after completion of Third year during the summer vacation vill work under supervision of institute guide and industrial guide. The ave to submit a report of the training undergone and make presentation duation committee constituted by the department. An internal evaluation ducted for examining the quality and authenticity of contents of the award the marks. based on compilation of work carried out related to machineries, instruments, state-of-art technologies, plant layout, Industry on chart, Management functions, Safety, rules and regulations, ation work, Industry standards, processes and tools used, fixtures and ed, Industrial automation, Computerization and software used in various ts, product flow, testing and quality control checks, painting and pack s, housekeeping practices as identified etc. and quality of work will be monitored by industrial and academic guide ning Report Format: Each student should have different industrial train	n ion ion ide ning
	 and its present by department Certificate: Al department. C Principal. The entire repo "Name o Area in reports in 	ation. The report should be of minimum 20 pages as per guideline iss time to time. Discipline should be maintained in industry. I students should attach standard format of Certificate as described by Certificate should have signatures of Guide, Head of Department rt should be documented as one chapter with details like f Industry with address along with completed training certificate" which Industrial training is completed All Students have to present to advidually. nts should attach MoU signed with industry.	the and

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO
CO↓															3
CO 1	1	-	-	-	2	-	-	-	2	2	1	2	1	1	1
CO 2	2	2	3	2	2	1	1	1	2	2	2	2	2	2	2
CO 3	1	1	2	2	1	2	2	3	2	2	2	2	1	1	1
CO 4	1	1	1	1	1	1	-	-	2	2	1	2	1	1	1
CO5	-	-	-	-	-	2	2	3	2	2	1	2	1	1	1
Avg	1.25	1.33	2	1.67	1.5	1.5	1.67	2.33	2	2	1.4	2	1.2	1.2	1.2
%	41.67	44.44	66.67	55.56	50	50	55.56	77.78	66.67	66.67	46.67	66.67	40	40	40

Knowledge Level	CA	ESE
Remember	-	-
Understand	-	-
Apply	10	5
Analyze	10	5
Evaluate	5	5
Create	-	10
TOTAL	25	25

Government College of Engineering, Karad		
Final Year (Semester – VII) B. Tech. Electronics and Telecommunication Eng	gineering	
EX2710: Project Work Phase 1		
Laboratory Scheme Examination		
Practical 2 Hrs./week CA	25	
Total Credits 1 ESE	25	
Course Outcomes (CO)		
Student Will be able to		
1 Analyze societal & environmental needs for finalizing solutions in modern ways.		T 4
 Analyze societal & environmental needs for finalizing solutions in modern ways. Propose optimize solutions for complex engineering problem. 		L4 L6
 Fropose optimize solutions for complex engineering problem. Evaluate the project in terms financial feasibility ,power consumption, technical performance, i 	markat	L0 L5
sustainability, flexibility, etc.	market	LJ
4 Create report about the new learning techniques, resources, and modern engineering tools.		L6
Course Contents		-
The project work will be carried a topic related to the Electronics & Telecommunication E	ngineering	
and allied fields. Selected topic need to be		
Development of innovative & productive idea in the area of Electronics & Telecom	munication	
Engineering & allied domain		
Economically feasible & may be modification in an existing electronics system.		
Practical need of the industry, which should involve system design aspect.		
Implementation of innovative work leading to comfort of human life (Interdisciplinary	Real-	
Life Applications) may lead to startup & patenting.		
Evaluation will be based on following criteria:		
Evaluation will be based on following criteria.		
Justification of domain, title, idea of project, Scope		
Literature review for last 3 Years to do the gap analysis.		
System Modeling, Requirement of Major Components, Hardware &Software		
Implementation of proposed project work (Roadmap, Methodology/Algorithms, block	schematic,	
Progressive chart, activity chart with deadline, Finalization of design, etc)		

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	1	2	2	2	2	2	3	2	2	2	2	2	2	2	2
CO 2	2	2	3	2	2	-	-	-	1	1	1	1	2	2	2
CO 3	2	2	1	1	1	-	2	-	1	2	3	1	2	2	2
CO 4	1	1	1	1	1	1	-	-	2	2	1	2	2	2	2
Avg	1.5	1.75	1.75	1.5	1.5	1.5	2.5	2	1.5	1.75	1.75	1.5	2	2	2
%	50	58.33	58.33	50	50	50	83.33	66.67	50	58.33	58.33	30	66.67	66.67	66.67

Knowledge Level	CA	ESE
Remember	-	-
Understand	5	-
Apply	10	10
Analyze	5	5
Evaluate	5	5
Create	-	5
TOTAL	25	25

	Go	vernment College of Engineering, Karad		
Final		VII) B. Tech. Electronics and Telecommunicati	on Engineer	ing
		icial Intelligence and Machine Learning Lab		
Laboratory Sche			nation Schem	e
Practical	2 Hrs/week	TA/CA	. –	
Total Credits	Audit	ESE	-	
Course Outcomes				
Student Will be abl				
		nniques to given data set		L3
	ferent clustering alg	brithms		L4
	cial neural network	on according to Antificial Intelligence and Machine I.		L6 L6
4. Create a rep	fort and presentation	on case study in Artificial Intelligence and Machine Le List of Experiment	arning	Lo
Experiment 1	Implement the Non	Parametric Locally Weighted Regression Algorithm in	n order to fit o	lata
	points.	rannette Locarry weighted Kegression Augorithin h		lata
Experiment 2	1	implement the naïve Bayesian classifier for a sample	e training data	ı set.
		cy of the classifier, considering few test data sets.		
Experiment 3	Â.	rking of the decision tree based ID3 algorithm.		
Experiment 4		n to cluster a set of data stored in a .CSV file. Use the	e same data se	et for
F	clustering using k-N			-
Experiment 5		mplement k-Nearest Neighbor algorithm to classify the	iris data set. S	Show
	both correct and wro			
Experiment 6		leural Network by implementing the Back propagation	algorithm and	l test
	the same using appr			
Experiment 7	<u> </u>	any suitable application.		
Experiment 8		any suitable application.		
Experiment 9	<u> </u>	SVM for classification with proper data set of your choi	ce.	
Experiment 10	**	Deep Learning algorithm.		
		esentation on one of case studies from :		
Case Study 1	-	Prediction (Survival Modelling)		
Case Study 2	Credit card Fraud A	-		
Case Study 3	Sentiment Analysis	or Topic Mining from New York Times		
Case Study 4	Sales Funnel Analy	is		
Case Study 5	Recommendation S	stems and Collaborative filtering		
Case Study 6	Customer Segmenta	tion and Value		
Case Study 7	Portfolio Risk Conf	ormance		
Case Study 8	Uber Alternative Ro	uting		
Case Study 9	AI in Cyber Securit	1		
Case Study 10	How online shoppir	g sites write Thousands of Email Subject Lines in Minu	ites	
List of				
Submission	Total much see f.F.	receiverants: 10		
1	Total number of E			
2	Total number of sh			
3	v	n/Case study Report: 01		
4	Seminar report: NA Field Visit Report:			
5	rieiu visit Report:	INA		

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	2	2	2	2	-	-	-	-	-	-	-	2	-	1
CO 2	2	2	2	2	2	-	-	-	-	-	-	-	2	-	1
CO 3	2	2	2	2	2	-	-	-	-	-	-	-	2	-	1
CO 4	2	2	2	2	2	-	-	-	2	2	-	-	2	-	1
Avg	2	2	2	2	2	-	-	-	2	2	-	-	2	-	1
%	66.66	66.66	66.66	66.66	66.66	-	-	-	66.66	66.66	-	-	66.66	-	33.33
1 – Low	1 – Low 2 – Medium3 – High														

Knowledge Level	CA	ESE
Remember		
Understand	5	
Apply	5	10
Analyze	5	5
Evaluate	5	5
Create	5	5
TOTAL	25	25

		T !! 1 X 7 //	Government College of					
		Final Year (S	Semester – VIII) B. Tech. EX2801: Legal Regu					
Teac	hing Sche	me				Examination Sch	omo	
Lectu	0	03 Hrs/week				CT – 1	15	
Tutor		00 Hrs/week				CT - 2	15	
	Credits	03				TA	10	
						ESE	60	
						Duration of ESE	02 Hrs	30 Min
	se Outcor							
	ent will be		1 ' T 1'					
			ne work in India	mmission	in India			L2 L5
		of the Indian bu	ce of Human Rights and Co		III IIIuia.			L3 L4
	laborate th							L4 L6
		cyber security	law					L5
			on on recent advances in law	for busines	s and securi	ty.		L6
		•	Course (•		Hours
Unit			tion to Indian legal system:					5
			egal system in India; Role of t					
	•		nt India; What is "Law"? Is le	gal Develop	oment Natio	onal or Planned? - U	se and	
Unit		ns of Law in So	and Human rights:					8
Umt			The Preamble; Fundamental R	ights: Dire	ctive princi	ples of State policy.		o
			mergency provisions – kinds	•	· ·			
			an Rights: Theoretical found				ghts;	
			n tradition and Western tradit					
			urt, High Courts, Statutory Co	ommissions	- NHRC, 1	NCW, NCM, NC-SO	C/ST etc.	
Unit	-	Business laws:					(. 1	9
			g and Nature of Contract, Agr oposals and acceptance- Defi				its and	
			cation, Invitation for Proposal		ous tornis,	Essential elements,		
			ip, sale of goods, pledge, mor					
			ny and its Nature and Scope, I		or Incorpor	ation of companies,		
	^		Debentures, Members and M	lembership	Rights.			
Unit		ctual Property		NA ' C			1	8
			of intellectual Property (IP), ion to the Indian Patent Syste					
		0	Patentability, : Patent Specif					
			tent Applications, Trademark,					
			conductor Integrated Circuits		•••			
		es and Farmers'						
Unit			and Information Technolog		.1	**** 1 *** 1 1		8
		-	Law Cybercrime, Legal issues					
			rnet, hacking, virus attacks, E verview of Data Protection: E) PR)	
			a, Payment Card Industry Data			. .	л к),	
		works – ISO 270	• •			C1 2 2 2) 2 CC ()		
Unit			Resolution Mechanism (ADR					4
		uction to Arbitra	ation, Mediation, Conciliation	and Negot	iation.			
	Books							
1. D	D. Basu,	Shorter Const	itution of India, Prentice H	all of India	1			
			utional Law, Wadhwa & Co					
			aria, Law relating to Protec				ing	
	1	<u> </u>	ts under International Law	and Indian	Law, Cen	tral Law Agency		
	rence Boo							
			act, Eastern Book		-			
			operty Rights, Universal La		0			
	11	a, Intellectual	Property Rights Law in Ind	ia, Asia La	aw House			
Usefu	ıl Links							

- 1. https://lawshelf.com/shortvideosview/contracts
- 2. https://www.youtube.com/watch?v=Bb9EBtlGx7w
- 3. https://lawshelf.com/videocoursesmoduleview/patent-basics-module-1-of-5/
- 4. https://www.youtube.com/watch?v=f9zfBd_9y9k

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	-	-	-	-	-	2	-	2	1	1	-	2	-	-	1
CO2	-	-	-	-	1	2	1	1	1	1	-	1	-	-	1
CO 3	-	-	-	1	1	1	-	2	1	1	-	2	-	-	1
CO 4	-	-	2	-	2	1	1	2	1	1	-	2	-	-	2
CO 5	-	-	2	-	2	2	1	2	2	1	-	2	-	-	1
CO 6	-	-	-	-	2	1	1	2	2	2	-	2	-	-	2
Total	-	-	4	1	8	9	4	11	8	7	-	11	-	-	8
Avg	-	-	2	1	1.6	1.5	1	1.88	1.33	1.16	-	1.83	-	-	1.33
%	-	-	66.66	33.33	53.32	49.99	33.33	62.66	44.32	38.66	-	60.99	-	-	44.32

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	5		2	10
Understand	5	5	3	10
Apply	5	5	3	15
Analyze	-	5	2	25
Evaluate	-	-	-	-
Create	-	-	-	-
TOTAL	15	15	10	60

			Government College				
		Final Year (S	Semester – VIII) B. Tech		and Telecommunica	tion	
Too	ching Sche	m 0	EX2802: Ro	botics	Examination	Sahama	
Lect		03 Hrs/week			CT – 1	15	
Tuto		01 Hrs/week			CT - 1 CT - 2	15	
	l Credits	04			TA	10	
					ESE	60	
					Duration of E	SE 02 Hrs	30 Min
Cours	e Outcome	s (CO)					
Stude	ent will be	able to					
			s types of industrial robots.				L2
			ssion system for robot drive				L2
	<u> </u>	A	actuator for specific applica				L5
			ciples and languages for a r		tem.		L3
			particular application using		. 1 1' .'		L3
6.	.	bot system and p se Contents	repare presentation on exis	ing process con	trol application.		L6
Unit			t and automations				Hours 8
Unit			t and automation: automation, Robotics in au	itomation Defir	nition of robot history	of Robotics	0
		• •	onents and Terminology of		•		
			on of Robots, Specification			or needoni,	
Unit			ver transmission Systems:				8
	Introd	uction of drive s	ystem, structure of drive sy	stem, Necessity	of drive system, Chara	acteristics of	
			sign consideration of drive s		c and Pneumatic System	ns, Electrical	
		•	vantages and limitations of	•			
		r transmission Sy	stems (Gear, Belt, Chains e	etc.)			
Unit		otic sensor system					8
			ensor Performance Char			•	
			h sensor, Slip sensors, Wi		sion sensors, Force sen	isor, Torque	
Unit			Criterion for sensor selection bot and End effectors:				8
Uiiit		•	s concepts and models, Ty	es of Controlle	rs feedback componen	ts Adaptive	0
			in Considerations of End				
			f gripper mechanism, Tools			× 11	
Unit	6 Kiner	natics of Robot	Manipulator:				6
			transformation using matri				
			Rotation matrix, Homogeno				
		•	Angle & Euler Transforma				
			-H) Representation & Disp on in Robotic Manipulation	lacement Matric	es for Standard Configu	irations,	
			•				10
Unit		t Programming:		Т (Г 1 D -			10
			rogramming, Programming Operating mode of robot, Jo				
		rs commands.	Sperating mode of robot, so	Jgging-Types, W	iotion commands, end e	and and	
			rogramming-basic commar	ds. motion cont	rol, hand control, prog	ram control.	
			tions, palletizing application				
			y in robotic applications	6	,		
	Case S	Study: Application	on of robot for Material har	dling and any in	dustrial process (Weldi	ing. Painting	
	etc.)			r			
	Books			1		D 1 11	a -
			R.N. Nagel, N.G. Odrey, "I	ndustrial Roboti	cs", Tata McGraw Hill	s Publication	, Second
	Edition, 20			·		, 1 .	1
			A Chmielewski, Michael N	egin, —Robotic	s Engineering: An Inte	grated Appro	ach∥, PH
	Learning, N rence Bool	ew Delhi, 2009.					
			cs and Automation Handbo	ok" CRC Prace	1st edition 2005		
<i>4</i> .							
	1 + 1 = 1 = 1 = 1		-rundamental Concents and	\mathbf{v}		avtla in a second	an <u>1010</u>
2. 4				•	Ford University Press, S	ixth impressi	on, 2010
2. A 3. F			mentals of Robotics Analy	•	•	ixth impressi	on, 2010.

- 1. https://nptel.ac.in/courses/112/105/112105249/- I.I.T, Kharagpur.
- 2 https://see.stanford.edu/Course/CS223A Stanford University, Stanford, California
- 3 http://nptel.ac.in/courses/112101099 I.I.T, Bombay

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	1	1										2		
CO2	2	1	2	1	1								3		1
CO 3	2	1	2	1	1								2		1
CO 4	2	2	3	2	2								2		2
CO 5	2	2	2	2	1								2		2
CO 6	2	3	3	2	2				2	2		1	2		2
Avg	2.00	1.67	2.17	1.6	1.4	0.00	0.00	0.00	2	2	0	1	2.17	0.00	1.6
%	66.67	55.56	72.22	53.33	46.67	0.00	0.00	0.00	66.67	66.67	0.00	33.33	72.22	0.00	53.33

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				
Understand	5	5	2	5
Apply	5	5	3	10
Analyze				20
Evaluate	5		3	15
Create		5	2	10
TOTAL	15	15	10	60

			Government (College of Eng	ineering, Kara	d		
		× *	/			ecommunication		
			EX2813: DSP Pro	cessor Architec	ture And Algori	ithms		
Tea	aching Sch	eme				Examination Sch	eme	
Lec	tures	02 Hrs/week				CT – 1	15	
Tut	orials	01 Hrs/week				CT – 2	15	
Tot	al Credits	03				ТА	10	
						ESE	60	
						Duration of ESE	02 Hrs	30 Min
		omes (CO)						
	dent will b							
1.			of a digital signal					L3
2.			various DSP proce					L2
3.			s of external memo			S		L3
4.			filtering algorithm					L3
5.		A	cessing and image					L5
6.	Create rep	ort and presentati	on on recent trends	in signal proces	sing			L5
				<u> </u>				
• •		· · · • •		Course Conten				Hours
Un	it 1 Arch	luction Desig Arc	grammable Digita	al Signal-Proces	Sors:	locks, Bus Archited	turo and	6
						grammability and		
			External Interfacin		ation Onit, 110	grannaonity and	Togram	
Un			Signal Processor					5
	Data	Addressing Mod			trol. Detail Stud	ly of TMS320C54	XX and	_
		320C67XX						
Un		ramming:					1 D	7
			mming, On-Chip mory Interface, Pa			e Operations, Exter	mal Bus	
Un			sic DSP Algorith		ce			5
UI					polation and Dec	cimation Filters (on	_	3
		ple in each case)	auton, i ny i nueis,		polation and Dec		0	
Un		•	lications Of DSP	Processor:				5
					erface Circuit, D	SP Based Bio-telem	netry	
	Recei	ver, A Speech Pro	cessing System, A	n Image Process	ing System.		2	
Note						DSP algorithms, in	terfacing	and
	applica	ations of DSP prod	essor using Mento	r DSP, TMS Boa	ards.	-	-	
	2. Group	of 3 to 4 student	will submit report a	and will give pre	esentation on rece	ent and relevant app	lications	in signal
	proces	ssing						
	Books							
1.	"Digital S	ignal Processing",	Avtar Singh and S	. Srinivasan, The	omson Learning,	2004.		
2.	DSP Proce	essor Fundamental	s, Architectures &	Features – Laps	ley et al. S. Chan	d & Co, 2000.		
	rence Boo			*	-			
			practical approach	, Ifeachor E. C.,	Jervis B. W Pear	rson Education, PH	I/ 2002	
2.	"Digital Si	gnal Processors",	B Venkataramani a	and M Bhaskar T	ГМН, 2002			
			gnal Processing", I		weily, 2007			
			onatham Stein, Jol					
5.	TMS320C	50, TMS320C54X	X, TMS320C6713	data books.				
	ul Links							
1.	http://www	v.ti.com/product/7	MS320C6713/tech	nicaldocuments				
2.	http://www	v.ti.com/tool/tmds	dsk6713					

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	1	-	-	1	-	-	-	-	-	-	-	2	2	-
CO2	2	-	2	-	2	-	-	-	-	-	-	-	-	1	2
CO 3	3	1	2	-	-	-	-	-	-	-	-	-	-	2	2
CO 4	3	2	2	1	2	-	-	-	-	-	-	-	-	2	1
CO 5	2	2	2	1	2	-	-	-	-	-	-	-	2	2	1
CO 6	2	2	2	1	2	-	-	-	2	2	-	-	2	2	1
Total	15	8	10	3	9	0	0	0	2	2	0	0	6	11	7
Avg.	2.5	1.6	2	1	1.8	0	0	0	2	2	0	0	2	1.833	1.4
%	83.33	53.33	66.67	33.33	60	0	0	0	66.67	66.67	0	0	66.67	61.1	46.67

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	-	-	-	10
Understand	05	-	-	10
Apply	05	05	02	10
Analyze	05	05	02	10
Evaluate	-	05	03	10
Create	-	_	03	10
TOTAL	15	15	10	60

			Government C	ollege of Enginee	ering, Kara	d		
		Final Year (S	Semester – VIII) l	B. Tech. Electron	ics and Tele	ecommunication		
			EX2823:Cl	oud Computing				
Te	eaching Sch	eme				Examination Sc	heme	
	ctures	02 Hrs/week				CT – 1	15	
Tu	itorials	01 Hrs/week				CT – 2	15	
То	tal Credits	03				ТА	10	
-						ESE	60	
						Duration of ESE		s 30 Min
С	ourse Outc	omes (CO)						
	udent will b							
1.			oud services for a g	iven application.				L2
2.		various cloud arc	-					L4
2. 3.	_		tware, and platform	as sorvicas				L4 L5
3. 4.		· · · · ·						L3 L4
4. 5.	-		for cloud computing					L4 L5
			dies for cloud comp	8				L5 L4
6.	Inspect st		services managemen	ll.				-
T T •			ourse Contents					Hours
Uni		luction to cloud	- 0	0 1 1	. 1	1 · 11		5
			-	, Components, deple	•		0.11	
	• •		of cloud computing.	Limitations of clou	id computing	. Grid Computing,	Gria	
T T •		ud Computing.	• • • •					
Uni			ervices and Applic			X7. 1 A 1.		6
	-	•	v	s ability, Infrastruct		**	ces,	
				efining Infrastructu		-		
			-	tform as a Service (I	PaaS), Defini	ing Identity as a Sei	rv1ce	
			pliance as a Service					
Uni			and Virtualization					6
				urity, Network and S				
		0.	U	tion, virtualization b		ervisors, porting		
			1 7 7	fining baselines and	Metrics.			
Uni	-	ring cloud servi						5
				ges, limits, virtualiz		-		
			overview, advantag	ges and functionalition	es, PaaS appl	ication frameworks	8	
	-	bal, Long Jump.			. .			
			Apps and Web Serv	ices, Azure web serv	vices, Amazo	on web		
		es(AWS)						ļ
Uni	it 5 Cloud	Administration	and Security Mar	agement				6
		-	-	nagement, cloud mai				
			•	a security, Identity a	•	•	,	
	Availa	bility manageme	ent in SaaS, IaaS, Pa	aS, Access Control,	Security Vul	Inerability, Patch		
	and Co	onfiguration Mar	agement, Security a	a Service of cloud	l, Future of S	ecurity in Cloud		
	compu	iting.						
Te	ext Books							
1.	Barrie Sos	sinsky, "Cloud C	omputing Bible", W	iley India Edition.				
2.	-	•	· •	, "Cloud Computing	g – A Practica	al Approach",		
		raw-Hill Edition						
	eference Bo							
1.		Rittinghouse, Jar rity" CRC Press.		loud computing: im	plementation	management	_	_
2.				g: Technology, Arch	nitecture Am	olications"		
4.	Jaulaiil	Smorr, Enterpri		5. reemology, Ale	meeture, Ap	pileariolis,		

	Cambridge University Press.										
3.	Christian Baun, Marcel Kunze, Jens Nimis, Stefan Tai, "Cloud Computing: Web-Based										
	Dynamic IT Services", Springer.										
Us	seful Links	eful Links									
1.	https://aws.amazon.com/training/										

$\begin{array}{c} PO \\ \rightarrow \\ CO \\ \downarrow \end{array}$	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO 1	2	2	2	-	-								2	1	-
CO2	2	1	-	1	-								2	-	-
CO 3	1	-	1	-	1								1	-	-
CO 4	2	-	2	1	-								1	-	1
CO 5	2	1	-	-	1								2	1	-
CO 6	2	-	2	-									1	-	-
total	11	4	7	2	2	-	-	-	-		-	-	9	2	1
Avg	1.83	1.33	1.75	1	1	-	-	-	-	-	-	-	1.5	1	1
%	61	44.3	58.3	33.	33.	-	-	-	-	-	-	-	50	33.33	33.33
			3	3	33										

Knowledge	CT	CT	TA	ESE
Level	1	2		
Remember				5
Understand	5	5	5	25
Apply	5	5	5	10
Analyze	5			10
Evaluate		5		10
Create				
TOTAL	15	15	10	60

			Governme	nt College o	f Engineeri	ing, Kara	d		
			Semester – VI	II) B. Tech.	Electronic	s and Tel	ecommunication	L	
]	EX2833: Real	Time Syste	m Design a	nd Applio	cations		
Teachi	ng Sche	me					Examination Sch	eme	
Lecture	_	02Hrs/week					CT - 1	15	
Tutoria	ls	01Hrs/week					CT - 2	15	
Total C	redits	03					ТА	10	
							ESE	60	
~		(22)					Duration of ESE	02 Hrs	30 Min
		nes (CO)							
	will be								L2
		l time system.	luling as per app	lightion					L2 L3
	-	•	e and communic						L3 L4
			face in real time						$\frac{L_{+}}{L_{2}}$
-			time system des		ent RTOS.				L5
			tion on real time	0		e studies.			L5
		×.			Contents				Hours
Unit 1	Introd	uction to Real	Time Systems :						6
	and Pri Real ti	vilege Levels, N me Systems Co	Memory Manage oncepts, Events	ement, Systen and Determ	n Calls, Devi inism,CPU J	ce Driver, l Utilization,	l Overview, Addre libraries. Real-Time Syster odel of Real-Time	n Design	
Unit 2	Static a priority	assumptions, Fizer tasks with- Sho		rsus Dynamic les and arbitra	ary response	times. Con	chedulability test f nmonly used appro ns.		
Unit 3	Main issues,l	Memory Datab Databases for Ha	•	pe Database Systems. Com	munications		ling, Concurrency twork Topologies F		
Unit 4	Real t Raspbe	ime hardware i erry Pi, Beaglebo RTOSES, Micr	interfaces: one, Edison , Po	orting real tim	ne operating S		boards and its Prog operating system		
Unit 5	Applic Linux Machir	ation and Case POSIX system, ne, an Adaptive	, RTLinux / RT. Cruise Control(2		÷		tomatic Chocolate oftware for Key in	•	5
Note;		Real time Inter	OS on hardware	, sensors, act			rial and USB port.		
Text Bo	ooks								
		/ "Real Time S	Systems",TMH,I	ndia 3rdRepr	int 2010				
			· · ·						
			ystems, Pearson					¥ ¥'11	
-			em Architecture	e, programmin	ng and desigr	n'', 3 rd edit	tion 2017, McGraw	v-Hill,	1
	nce Boo								
1. Lap	ante P. A	A., Real Time S	Systems Design a	and Analysis,	, 4th Edition,	Wiley & S	ons, Incorporated,	John	
		Kopetz, "Real-T ries)", Springer,		esign Princip	les for Distri	buted Emb	eddedApplications	(Real-Tir	ne

3.	Abraham Silb 2008.											
Use	eful Links											
1.	IEEETechnical	CommitteeonReal-timesystems										
2.	Ada'95ReferenceManual											

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	3	2	2	1	1								2		1
CO2	3	1	2	1	1								2		1
CO 3	2	1			1								2	1	
CO 4	2	1	2		1								2		2
CO 5	2	1	2	1									2		1
CO 6	2	2	2		1				2	2		1	2		1
Total	14	8	10	3	5	-	-	-	2	2	-	1	12	1	6
Avg	2.33	1.33	2	1	1.25	-	-	-	1	1	-	1	2	1	1.2
%	77.66	44.33	66.66	33.33	41.66	-	-	-	33.33	33.33	-	33.33	66.66	33.33	40

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				10
Understand	05			10
Apply	05	05		10
Analyze	05	05	05	10
Evaluate		05	05	10
Create				10
TOTAL	15	15	10	60

2. Utiliz	Scheme 02 Hrs/week 01 Hrs/week	emester – VIII) B. Tech. Electronics EX2843: Agro Instrumentation		eme	
Lectures Tutorials Total Crea Course O Student w 1. Illustra 2. Utiliz	02 Hrs/week 01 Hrs/week	EA2045. Agro mistrumentation	Examination Sch	eme	
Lectures Tutorials Total Crea Course O Student w 1. Illustra 2. Utiliz	02 Hrs/week 01 Hrs/week				
Total Crea Course O Student w 1. Illustra 2. Utiliz			CI - I	15	
Course O Student w 1. Illustra 2. Utiliz	dits 03		CT – 2	15	
Student w 1. Illustra 2. Utiliz			TA	10	
Student w 1. Illustra 2. Utiliz			ESE	60	
Student w 1. Illustra 2. Utiliz			Duration of ESE	02 Hrs	30 Min
 Illustra Utiliz 					
2. Utiliz	ate Environmental is	sues			L2
		chniques in agro industry.			L3
. . µ 10 VIC		ivity enhancement and paste control.			L5
4. Identif	fy waste management	& dispose control system.			L3
		nent & rain harvesting system.			L3
6. Creat	te Report and presentat	ion on recent trends and development in a	gro industry through visits.		L6
		Course Contents			Hours
	6 6	in agricultural sector			03
		bilities and professional ethics, engin			
		I issues, various government policies gineering for productivity enhancement		ment	
	Sensor technology for				05
		ectrical conductivity, gas analysis, humidi	ty, leaf area, chlorophyll cont	ent,	
	and soil moisture & ten	nperature.			
	Precision Farming				07
		ision farming. GIS/GPS positioning system			
		g, soil sampling and analysis. Computers a es and conditions. Role of electronics in fa			
		nstrumentation in Agriculture	uni machinery for precision r	arnnig.	07
		nonitoring – moisture measurement – c	apacitive, infrared reflectar	nce and	07
r	esistance. Monitorin	g soil and weather – measurement of s	soil properties and meteoro	ological	
		on control systems. Instruments for cro			
s f	arming Instruments	rop spraying – flow control. Yield more for protected cultivation – green house	environment control – trans	sducers	
		struments and systems for crop handli			
Unit 5 A	Advance Applications	of in Agriculture			06
	5	of modeling and control of Greenho			
		for Greenhouse. Crop Preservation : Im			
		of plants, Drying process for preservation ntrol system for grape drying process, S			
		Robotics, Artificial Intelligence (AI) bas			
	-	tem, agricultural water pump monitoring sy	÷ .	-	
	ources, Greenhouse sy				
		should be elaborated with block schem		. 1	
	student should visit ar submit report on that.	y hi tech Farm or visit modern agree ins	strument manufacturing indus	stry and	
		on different applications in agricultural sec	tor		
Text Boo		in arrelent applications in agricultural see			
		Control Instrumentation Technology	1. 8th Edition Pearson Ed	ucation	
-			n, our Edition, rearbon Ed	ucution	
Reference		sion farming guide for agriculturalist.			T
		ntal of Geographic Information System	I John Willy & sons New	York D	l
S.K.		nui or Geographic information System	i. John Whily & John, New	101K, D	atta
		ess Controll; New Age International Pu	blisher.		
		_		tions P	
		l of Soil & Water conservation Engine	ening. Oxford & IBH Co. S	ngma &	-
Jagmo		supervisory control and data acquisitio	n ISA Dublication		
					<u> </u>
Useful Li		atch?v=iUNNec3U_Pc			1

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	1	1	1	1	-	2	2	2				2			2
CO 2	2	2	2	2	3	1	2	2				2			2
CO 3	2	2	2	2	2	1	2	2				2			2
CO 4	1	2	2	2	1	2	2	2				2			2
CO 5	1	2	2	2	1	2	2	2				2			2
CO 6	2	2	2	2	2	2	2	2	2	2		2			2
Total	9	11	11	11	9	10	12	12	2	2		12			12
Avg	1.5	1.83	1.83	1.83	1.8	1.66	2	2	2	2		2			2
%	50	61.11	61.11	61.11	60	55.55	66.66	66.66	66.66	66.66		66.66			66.66

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				10
Understand	05			10
Apply	05	05	03	10
Analyze	05	05	02	10
Evaluate		05	02	10
Create			03	10
TOTAL	15	15	10	60

Final Year (Semester – VIII) B. Tech. Electronics and Telecommunication EX2853: Computer Vision Teaching Scheme Examination Scheme	
*	
reaching Scheme	
Lectures 02 Hrs/week CT – 1 15	
Lectures 02 Ins/week $CT = 1$ 13 Tutorials 01 Hrs/week $CT = 2$ 15	
Total Credits03TA10	
ESE 60	
Duration of ESE 02 Hrs 30	0 Min
Course Outcomes (CO)	
Student will be able to	
1. Relate human eye & camera operation.	L2
2. Analyze digital image processing filter functions	L4
3. Design vision systems for applications in industrial automation and robotics.	L3
4. Compare low- and high-level vision.	L2
 Utilize the Open-cv or python library functions in computer vision application. Create the report and presentation of recent trend in computer vision applications 	L1 L3
	Hours
Unit 1 Vision Systems:	6
Basic Elements of visual perception, structure of human eye, image formation in the eye, pinhole	0
cameras, color cameras, image formation model, imaging components and illumination techniques,	
picture coding, basic relationship between pixels, Camera-Computer interfaces.	
Unit 2 Low-Level Vision:	6
Image representation, gray level transformations, Histogram equalization, image subtraction, image	
averaging, Filters, smoothing spatial filters, sharpening spatial filters, smoothing frequency domain	
filters, sharpening frequency domain filters, edge detection. Unit 3 Higher – Level Vision:	6
Unit 3 Higher – Level Vision: Segmentation, Edge linking and boundary detection, Thresholding, Region-oriented segmentation, the	0
use of motion, Description, Boundary Descriptors, Regional Descriptors, Recognition, Decision-	
Theoretic methods, structural methods.	
Unit 4 Robot Vision:	4
Basic introduction to Robotic operating System (ROS), Robotic Assembly Sensors and Intelligent	
Sensors, visual servo-control, Installing and testing ROS camera Drivers	
Unit 5 Applications of Vision Systems:	6
Camera Calibration, Stereo Imaging, transforming sensor reading, Mapping Sonar Data, aligning laser	
scan measurements, Vision and Tracking, Following the road, Iconic image processing, Multiscale	
image processing, Video Tracking, learning landmarks, Landmark spatiograms, K-means Clustering, EM Clustering, Kalman Filtering.	
Note: Tutorial hours will be utilized for learning and development of applications in computer vision	
Python programming for Computer Vision:	<i>)</i> 11.
Introduction to OpenCV image processing library, open cv command and functions related with image	ge and
vision, The OpenCV Python Interface, OpenCV Basics, Processing Video, Tracking, The cv_bridgePa	ickage,
Robotic operating System (ROS) to OpenCV, More Examples	
Text Books	
1. K. S. Fu, R. C. Gonzalez, CSG. Lee, —Robotics control, sensing, vision and Intelligencel, McGraw Hill Edu	ication
 Pvt. Ltd., 2013. 2. Damian M Lyons, —Cluster Computing for Robotics and Computer VisionI, World Scientific, Singapore, 201 	11
2. Damian M Lyons, —Cluster Computing for Robotics and Computer Visioni, World Scientific, Singapore, 201 Reference Books	11.
1. Carsten Steger, Markus Ulrich, Christian Wiedemann, —Machine Vision Algorithms and Applicationsl, WILI	FY-
VCH, Weinheim, 2008.	L/ I -
 Janaki Raman. P.A., "Robotics and Image Processing", Tata McGraw-Hill Publication, 1st edition, 1995. 	
3. Richard D Klafter, Thomas A Chmielewski, Michael Negin, —Robotics Engineering: An Integrated Approach	ı∥, PHI
Learning, New Delhi, 2009	,
Useful Links	
1. https://nptel.ac.in/courses/106/105/106105216/ - I.I.T, Kharagpur	
2. https://nptel.ac.in/courses/108/103/108103174/ - I.I.T, Guwahati	
 https://nptel.ac.in/courses/noc/103/103/103/104/ - 1.1.1, Guwallal https://onlinecourses.nptel.ac.in/noc/19_cs58/preview- I.I.T, Kharagpur https://nptel.ac.in/noc/courses/noc19/SEM2/noc19-cs58/ - I.I.T, Kharagpur 	

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	2	1	1										2		
CO2	2	2	2	1	1								2		
CO 3	2	1	2	1	1								2		2
CO 4	2												2		
CO 5	3	2	1	1	1								2		2
CO 6	2	2	2	1					2	2		1	2		1
Avg	2.17	1.6	1.6	1	1	0.00	0.00	0.00	2	2	0.00	1	2	0.00	1.67
%	72.22	53.33	53.33	33.33	33.33	0.00	0.00	0.00	66.67	66.67	0.00	33.33	66.67	0.00	55.56

Knowledge Level	CT 1	CT 2	TA	ESE
Remember	5		3	10
Understand	5	5	2	10
Apply		5	3	20
Analyze	5	5	2	20
Evaluate				
Create				
TOTAL	15	15	10	60

				e of Engineering, Kara			
		Final Year (S	Semester – VIII) B. Teo		lecommunication		
			EX2863: Cybe	r Security			
	ing Sche				Examination Sch		
Lectur Tutoria		02 Hrs/week			CT - 1 CT - 2	15	
	Credits	01 Hrs/week 03			TA	15 10	
Total	credits	03			ESE	60	
					Duration of ESE		30 Min
Cours	e Outcon	nes (CO)			Duration of LSL	021113	50 IVIII
	nt will be	· · · · · ·					
		cyber threats					L3
		•	in Mobile and Wireless D	evices			L2
			used in Cyber crime				L4
4. M	lake use o	f information an	d data to serve as digital e	vidence			L3
			lications of cybercrime				L6
6. Cr	reate a rep	port and presentation	ation on case study in Cyb				L6
			Cours	e Contents			Hours
Unit 1							_
			nation Security, Cybercrim				
			he Attacks, Social Engine	e i	yper cate and Cybe	ercrimes,	
Unit 2		and Wireless	Cybercrime, Attack Vector	[
Unit 2			edit Card Frauds in Mobi	le and Wireless Comput	ing Fra-Security Ch	nallenges	6
			ices, Registry Settings for				
			Cell Phones, Mobile D				
			es for Handling Mobile, Or				
	•	ting Era.	C I				
Unit 3			sed in Cybercrime:				
			onymizers, Phishing, Pass				
			and Backdoors, Steganog Wireless Networks, Phisl				
	Theft)	Jw, Attacks off	whereas herworks, Filisi	ing and identity Thert,	rinshing, identity i	nen (iD	
Unit 4		iter Forensics:					
01110	-		ce, Cyber forensics and D	igital Evidence, Forensic	s Analysis of E-Mai	l, Digital	
			Chain of Custody Cond				
			, Setting up a Computer F				
			d Steganography, Relevan Networking Sites: The				
			e, Challenges in Compute				
		ng, Antiforensics		r rorensies, speciar roo	is and Teeninques, T	orensies	
Unit 5	5 Intrusi	on Detection a	nd Prevention System:				
			ection, Analysis Approac				
			istributed or Hybrid Intru	sion Detection, Intrusion	Detection Exchange	e Format	8
		oots, Example S	ystem: Short , Firewall Characteristics a	nd Access Policy Types	of Firewalls Firewal	1 Basing	
			d Configurations, Intrusi				
		ement Products.			,		
Note	Tutori	als will be base	d on -				
			mmand Line - The Linux F				
			tion - Managing Installe				
			he Swiss Army Knife of T				
			tudy Topics on Cyber Cri				
		Digital Forensi y stake holders.	cs Cases – Bridging the C	raps in Cyber Crime Inve	esugations between t	ne cyber	
Text B		y stake nonders.					
		le. Sunit Relanu	re, "Cyber Security", Wild	ev India, New Delhi	1		
-							
			Systems Security", Wiley				
			ciples of Computer Secu	rity: Fourth Edition, Mc	GrawHill, 2016		1
	ence Boo					D	
			raphy and Network Secu				on
2. Ac	myut S. C	Joudole, web I	Cechnologies: TCP/IP, W	eo/Java Programming, a	na Cioua Computin	ig, 1 ata	

	McGraw-Hill Education, 2013									
Use	ful Links									
1.	https://www.newhorizons.com/promotions/cybersecurity-ebooks									
2.	https://www.coursera.org/learn/introduction-cybersecurity-cyber-attacks#syllabus									
3.	https://www.udemy.com/course/cyber-security-kali-linux-course/									
4.	https://www.udemy.com/course/kali-linux-tutorial-for-beginners-en	/								

$PO \rightarrow$	PO 1	PO 2	PO 3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	1	2	-	2	1	2	-	-	-	-	-	2	-	-	-
CO2	1	2	-	2	-	2	-	-	-	-	-	2	-	-	-
CO 3	2	2	1	2	2	-	1	-	-	-	-	-	-	-	-
CO 4	-	-	2	2	2	1	1	-	-	-	-	1	-	-	-
CO 5	-	2	1	2	-	2	-	-	-	3	-	1	-	-	-
CO 6	-	2	1	2	2	-	-	-	2	2	-	2	-	-	-
	1.33	2	1.25	2	1.75	1.75	1	-	2	2.5	-	1.6	-	-	-
%	44.33	66.66	41.66	66.66	58.33	58.33	33.33	-	66.66	83.33	-	53.33	-	-	-

Knowledge Level	CT 1	CT 2	TA	ESE
Remember				
Understand	5			10
Apply	5	5	2	15
Analyze	5	5	2	15
Evaluate		5	2	10
Create			4	10
TOTAL	15	15	10	60

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO
CO↓															3
CO 1	2	1	1		2					1					
CO 2	2	3	2	3	2								3		2
CO 3	3		1	1									2		1
CO 4	2	2	2	2	2				2	2			3		2
Avg	2.25	2	1.5	2	2	0	0	0	2	1.5	0	0	2.67	0	1.67
%	75.00	66.67	50.00	66.67	66.67	0.00	0.00	0.00	66.67	50.00	0.00	0.00	88.89	0.00	55.56

Knowledge Level	CA	ESE
Remember		
Understand		
Apply	15	15
Analyze	20	20
Evaluate		
Create	20	20
TOTAL	50	50

			vernment Colle						
	Final Yea		VIII) B. Tech.				n Engir	neering	
		EX280	5 :Project Worl	x Phase 2(Acad	lemic Mode	1 C C C C C C C C C C C C C C C C C C C			
	ratory Scheme					Examina	tion Sch		
Practi		8 Hrs./week				CA		150	
	Credits	16				ESE		150	
	se Outcomes (C	.0)							
Studen	t Will be able to		ntal needs for fin						L4
1. 2.			complex engineeri	0	s in modern	ways.			L4 L6
<u> </u>			ancial feasibility	01	tion technica	1 performa	nca mar	·kat	L5
5.	sustainability, f			power consumpt		li periorna	nee, mai	KCl	LJ
4.			gineering solution	s with necessary	presentation	by entire	project te	eam	L5
5.			system & report						L6
	modern engine		sjoteni et report				•••••••••••••••••••••••••••••••••••••••		20
	C	C	Cou	rse Contents					
	Student	ts should							
			uirement & availa						
			ponents requireme		specification	of items u	sed in pr	roject	
			ilization & availa						
			ect work in peer 1	reviewed journal	s/ conference	e identified	by depa	artment	
	(manda	•							
		•	rd format using ec	•			2	,	
			Project Report &		ished by usin	ng Turnitin	software	e (up to	
		-	ll check & certify		1 1 /		• / 1	111	
	awarde	d to project tean	t of Certificate as and not to indivi	dual student.	•	ent. Certif			
			ion ESE shall con			sed on the r	eport sub	omitted	
	•		ne demonstration of		•				
			tion (ESE) will be						
			rking as a senior a	and other externa	il examiner p	referably f	rom Indu	istry or	
		ernal Academic							
	Evaluation will	i de dased on fo	llowing criteria:						
	Justific	ation of domain	title & Idea of pro	oject & Scope					
	• Literatu	ure review for la	st 3 Years to do th	e gap analysis.					
	• System	Modeling, Req	irement of Major	Components, Sc	oftware or Flo	owchart			
	• Implem	nentation of prop	osed project work	(Roadmap, Meth	hodology/Alg	gorithms, b	lock sch	ematic,	
	-		ity chart with dead						
			ive concepts/New			-			
				liceus meorporu	ted in the pro	Jeet work			
	Cutting	, edge software	hardware tools use	ed for the project	work				
			- (- () - ((1000/ 0	-1-(' '	1		
		÷ .	ntation/completion			-	-		
			n project work. (Su of project, etc.)	urvey paper, proc	of of concept.	, innovative	e idea of		
	of every week	activity should	ry should be main be mentioned for o	continuous evalu					
	snould be pres	sented at the time	e of End Semester	examination					

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO↓															
CO 1	1	2	2	2	2	2	3	2	2	2	2	2	2	2	2
CO 2	2	2	3	2	2	-	-	-	1	1	1	1	2	2	2
CO 3	2	2	1	1	1	-	2	-	1	2	3	1	2	2	2
CO 4	2	2	2	2	2	-	-	-	3	3	2	1	2	2	2
CO5	1	1	1	1	1	1	-	-	2	2	1	2	2	2	2
Avg	1.6	1.8	1.8	1.6	1.6	1.5	2.5	2	1.8	2	1.8	1.4	2	2	2
%	53.33	60	60	53.33	53.33	50	83.33	66.67	60	66.67	60	46.67	66.67	66.67	66.67

Knowledge Level	CA	ESE
Remember	-	-
Understand	20	10
Apply	30	20
Analyze	30	30
Evaluate	20	40
Create	50	50
TOTAL	150	150

			ernment Colle					
	Final Year (Sem						Engineering	
		EX2806 :	: Project Worl	x Phase 2(In	dustry Mode	·		
	ratory Scheme						on Scheme	
Pract						CA	200	
	Credits 16					ESE	200	
	se Outcomes (CO) t Will be able to							
1.	Analyze societal & env	vironment	al needs for fin	lizing solutio	ns in modern	Wawe		L4
2.	Propose optimize solution					ways.		L4 L6
3.	Evaluate the project in the				ntion technica	1 performan	re market	L5
	sustainability, flexibility		ierar reasionity,	power consum	iption, teennea	i periorman	ee, market	23
4.	Explain effectively prop		neering solution	s with necessa	ry presentation	by entire pr	oject team	L5
5.	Create a prototype mode	· ·	v			· ·	0	L6
	modern engineering to	ools.			-	-		
			Cours	se Contents				
	Students should							
	• List out the mate	-		•				
	Identify optimize				t specification	of items use	d in project	
	Identify various					1 10 11		
	• Publish a paper of	on project	work in peer rev	newed journal	s/ conference 10	dentified by	department	
	(mandatory)		fo	ting to als (M	ano a off mond of	* 1040*)		
	Make a report inCheck for plagia		•	•			ftware (up to	
	• Check for plaga 10 % allowed, g			baper to be put	Sinshed by using	g i urmun so	itware (up to	
			f Certificate as	prescribed by	the departme	ent Certifica	te should be	
	awarded to proje				the deputitie		ae should be	
	• The entire report				vith details like			
	1) "Name of In					ficate"		
			rial training is o	completed All	Students have	e to present	their reports	
	individually.							
	3) All students	s should att	ach MoU signed	l with industry	•			
-	• End Compostor Ex	vomination	ESE chall const	at of an anal a	romination has	d on the ren	ant automittad	
	• End Semester Ex by the candidate					ed on the rep	on submitted	
	 End Semester E. 			1 5	•	examiners	consisting of	
	preferably the gu			•	•		Ų	
	the external Aca		•			•••••••••••		
	Evaluation will be base	ed on follo	wing criteria:					
			5					
	Justification of d	domain, tit	le & Idea of proj	ect & Scope				
	• Literature review	w for last 3	³ Years to do the	gap analysis.				
	• System Modelin				Software or Flov	wchart		
	Implementation	e 1	C C				ock schematic	
	Progressive char			-		-	ook senemane,	
	-							
	Innovative idea/I	innovative	e concepts/New]	ueas incorpor	ated in the proj	ect work		
	• Cutting edge sof	ftware ,har	dware tools used	l for the proje	ct work			
	Percentage of im	nplementat	tion/completion	of project wor	k (100% Comp	letion is exp	ected)	
	Research publica	-	-	- ·	-	-		
	implementation			v 1 °T , P1 '	······································		r J,	
	-							
	Note -Note -Hardcopy of							
	report of every week ac should be presented at t				us evaluation di	uring the ter	m. This diary	
L	should be presented at t	the time of		Aummanon				

$PO \rightarrow$	PO 1	PO 2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO ₂	PSO3
CO↓															
CO 1	1	2	2	2	2	2	3	2	2	2	2	2	2	2	2
CO 2	2	2	3	2	2	-	-	-	1	1	1	1	2	2	2
CO 3	2	2	1	1	1	-	2	-	1	2	3	1	2	2	2
CO 4	2	2	2	2	2	-	-	-	3	3	2	1	2	2	2
CO5	1	1	1	1	1	1	-	-	2	2	1	2	2	2	2
Avg	1.6	1.8	1.8	1.6	1.6	1.5	2.5	2	1.8	2	1.8	1.4	2	2	2
%	53.33	60	60	53.33	53.33	50	83.33	66.67	60	66.67	60	46.67	66.67	66.67	66.67

Knowledge Level	CA	ESE
Remember	-	-
Understand	20	10
Apply	40	40
Analyze	40	40
Evaluate	40	45
Create	60	65
TOTAL	200	200